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THE CONVERGENCE OF AN ITERATION METHOD FOR THE PLATE UNDER THE ACTION OF A SYMMETRIC LOAD

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Abstract. We consider a boundary value problem for a Timoshenko system of nonlinear ordinary differential equations describing the plate static behavior. The unknown functions u, w and ψ are the longitudinal and the transverse displacement and the angle of rotation of the normal of the plate. The functions u and ψ are expressed explicitly through the function wfor which a nonlinear integro-differential equation with a boundary condition is written. To approximate the problem solution for w, the Galerkin method is used. It leads to a nonlinear system of algebraic equations that is solved by the Jacobi iteration method. The convergence of the iteration method is established and the error estimate is obtained.

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1 Introduction. If from the system of Timoshenko equations for a shell given in [2, p. 42], we discard the variables t and y and assume $k_x = k_y = 0$, we obtain a onedimensional system of equations which characterizes the static state of the plate under the action of axially symmetric load. It has the form

$$u'' + \frac{1}{2} (w'^2)' + p(x) = 0,$$

$$k_0^2 \frac{Eh}{2(1+\nu)} (w'' + \psi') + \frac{Eh}{1-\nu^2} \left[\left(u' + \frac{1}{2} w'^2 \right) w' \right]' + q(x) = 0, \quad (1)$$

$$\frac{h^2}{6(1-\nu)} \psi'' - k_0^2 (w' + \psi) = 0, \quad 0 < x < 1.$$

Suppose the following boundary conditions are fulfilled

$$u(0) = u(1) = 0, \quad w(0) = w(1) = 0, \quad \psi'(0) = \psi'(1) = 0.$$
 (2)

Here the displacements u = u(x), w = w(x) of the plate midplane and the angle of rotation $\psi = \psi(x)$ of the normal to the midplane are the unknown functions to be determined, whereas the forces p(x) and q(x) are the given ones. E is Young's modulus, h is the plate thickness, k_0 is the lateral shear coefficient and ν is the Poisson ratio, $0 < \nu < 0.5$. Note that these equations can also be obtained from Timoshenko equations for a plate in [1, p. 24]. Using the first and the third equation from (1) and taking into account the respective

boundary conditions from (2), the functions u(x) and $\psi(x)$ can be expressed through the function w(x) as follows

$$u(x) = \int_0^1 G_u(x,\xi) w'^2(\xi) d\xi + \int_0^1 G_p(x,\xi) p(\xi) d\xi,$$

$$\psi(x) = \int_0^1 G_\psi(x,\xi) w'(\xi) d\xi,$$
(3)

where

$$G_u(x,\xi) = \begin{cases} \frac{1}{2} (x-1), & x > \xi, \\ \frac{1}{2} x, & x < \xi, \end{cases} \qquad G_p(x,\xi) = \begin{cases} \xi(1-x), & x > \xi, \\ x(1-\xi), & x < \xi, \end{cases}$$
$$G_\psi(x,\xi) = \begin{cases} -\frac{\sigma}{\sinh\sigma} \cosh\sigma(x-1)\cosh\sigma\xi, & x > \xi, \\ -\frac{\sigma}{\sinh\sigma} \cosh\sigma x\cosh\sigma(\xi-1), & x < \xi, \end{cases}$$

and $\sigma = \frac{k_0}{h}\sqrt{6(1-\nu)}$. Applying (3) in the second equation of system (1), we come to the equation for the function w(x)

$$\frac{Eh}{1-\nu^2} \left[\left(\frac{1-\nu}{2} k_0^2 + \frac{1}{2} \int_0^1 w'^2 dx + \int_0^1 (1-x)p(x) \, dx - \int_0^x p(\xi) \, d\xi \right) w'' - p(x)w' \right] \\ - \frac{3Ek_0^4}{h\sinh\sigma} \frac{1-\nu}{1+\nu} \left(\sinh\sigma(x-1) \int_0^x \cosh\sigma\xi \, w'(\xi) \, d\xi + \sinh\sigma x \int_x^1 \cosh\sigma(\xi-1)w'(\xi) \, d\xi \right) + q(x) = 0,$$
(4)

to which we add the boundary condition from (2)

$$w(0) = w(1) = 0. (5)$$

Thus problem (1), (2) reduces to problem (4), (5) for the function w(x). After solving the latter problem, we construct the functions u(x) and $\psi(x)$ by explicit formulas of form (3).

Now let us consider the question of approximate solution of problem (4), (5).

The approximation of w(x) is written as the finite sum

$$w_n(x) = \sum_{i=1}^n \frac{1}{i\pi} w_{ni} \sin i\pi x,$$
 (6)

where, in case we use the Galerkin method, the coefficients w_{ni} satisfy the nonlinear system of equations

$$\left(p_{1i} + p_2 + \sum_{j=1}^n w_{nj}^2\right) w_{ni} + \sum_{j=1}^n p_{3ij} w_{nj} + \frac{1}{i} q_i = 0, \quad i = 1, 2, \dots, n.$$
(7)

Here the following notation is used

$$p_{1i} = \frac{1}{\frac{1}{2k_0^2(1-\nu)} + \frac{3}{(h\pi i)^2}}, \quad p_2 = 4 \int_0^1 (1-x)p(x) \, dx,$$
$$p_{3ij} = -8 \int_0^1 \left(\int_0^x p(\xi)d\xi\right) \cos i\pi x \cos j\pi x \, dx, \quad q_i = -\frac{8(1-\nu^2)}{Eh\pi} \int_0^1 q(x) \sin i\pi x \, dx.$$
(8)

We will solve system (7) by using the Jacobi iteration method

$$\left(p_{1i} + p_2 + w_{ni,k+1}^2 + \sum_{\substack{j=1\\j \neq i}}^n w_{nj,k}^2 \right) w_{ni,k+1} + p_{3ii} w_{ni,k+1} + \sum_{\substack{j=1\\j \neq i}}^n p_{3ij} w_{nj,k} + \frac{1}{i} q_i = 0, \quad (9)$$

$$k = 0, 1, \dots, \quad i = 1, 2, \dots, n,$$

where $w_{ni,k+l}$ is the (k + l)-th approximation of w_{ni} , l = 0, 1. To realize iteration (9), we have to solve a cubic equation with respect to $w_{ni,k+1}$. Therefore, using the Cardano formula $w_{ni,k+1}$ can be written in the explicit form

$$w_{ni,k+1} = \sigma_{i,1} - \sigma_{i,2}, \quad k = 0, 1, \dots, \quad i = 1, 2, \dots, n,$$
 (10)

where

$$\sigma_{i,l} = \left[(-1)^l \frac{s_i}{2} + \left(\frac{s_i^2}{4} + \frac{r_i^3}{27}\right)^{\frac{1}{2}} \right]^{\frac{1}{3}}, \quad l = 1, 2,$$
$$r_i = p_{1i} + p_2 + p_{3ii} + \sum_{\substack{j=1\\j \neq i}}^n w_{nj,k}^2, \quad s_i = \frac{1}{i} q_i + \sum_{\substack{j=1\\j \neq i}}^n p_{3ij} w_{nj,k}.$$

Let us estimate the error of the iteration process of the function w(x). By this error we mean the difference between the function (7) and the function $w_{n,k}(x) = \sum_{i=1}^{n} \frac{1}{i\pi} w_{ni,k} \sin i\pi x$, obtained during the realization of the iteration process (10), i.e. the function $w_n(x) - w_{n,k}(x)$.

Theorem. Suppose that the functions p(x), q(x) and constants ν . E, h, k_0 are such that

$$\left(\frac{1}{2k_0^2(1-\nu)} + \frac{3}{(hi\pi)^2}\right)^{-1} > \left|4\int_0^1 (1-x)p(x)\,dx\right| - 8\int_0^1 \left(\int_0^x p(\xi)\,d\xi\right)\cos^2 i\pi x\,dx \, \left|, \ i = 1, 2, \dots, n\,, \right.$$
(11)

and

$$\frac{1}{2} \max_{1 \le j \le n} \sum_{\substack{i=1\\i \ne j}}^{n} \frac{1}{c_i} |p_{3ij}| + \frac{1}{2} \sum_{i=1}^{n} \frac{1}{c_i} \left(2 \frac{|q_i|}{i\sqrt{c_i}} + \left(\sum_{\substack{j=1\\j \ne i}}^{n} p_{3ij}^2 \right)^{\frac{1}{2}} \right) < \Delta < 1.$$
(12)

Then there exists a unique solution w_{ni} , i = 1, 2, ..., n, of system (7) to which the sequence of approximations $w_{ni,k}$ of the iteration method converges as $k \to \infty$. For the error of the iteration method we have

$$\left\| \frac{d^{l}}{dx^{l}} \left(w_{n}(x) - w_{n,k}(x) \right) \right\|_{L_{2}(0,1)} \leq \frac{\Delta^{k}}{\sqrt{2} \pi^{1-l}(1-\Delta)} \sum_{i=1}^{n} |w_{ni,1} - w_{ni,0}|, \ l = 0, 1, \ k = 0, 1, \dots$$

Note that instead of requirements (11) and (12) we can use more rigid but easily verifiable conditions

$$c = \left(\frac{1}{k_0^2(1-\nu)} + \frac{6}{(h\pi)^2}\right)^{-1} - \left(\frac{5}{\sqrt{3}} + \frac{\sqrt{2}}{\pi}\right)p_0 > 0 \tag{13}$$

and

$$\frac{1}{2c} \left(\left(\frac{1}{\pi} + \left(\frac{1}{\sqrt{2}} + \frac{4}{\pi} \right) n + \sqrt{2}(n-1)n \right) p_0 + 8\sqrt{\frac{2}{c}} \frac{1-\nu^2}{Eh\pi} q_0 \right) \sum_{i=1}^n \frac{1}{i} < \Delta < 1, \quad (14)$$

where $p_0 = \left(\int_0^1 p^2(x) dx\right)^{\frac{1}{2}}$, $q_0 = \left(\int_0^1 q^2(x) dx\right)^{\frac{1}{2}}$. The conditions (11) and (12) as well as (13) and (14) are fulfilled for sufficiently small functions p(x) and q(x).

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