

# ABOUT ONE PROBLEM OF POROUS COSSERAT MEDIA FOR SOLIDS WITH TRIPLE-POROSITY

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## *Abstract*

The purpose of this paper is to consider the two-dimensional version of the linear theory of elasticity for solids with triple-porosity in the case of an elastic Cosserat medium. Using the analytic functions of a complex variable and solutions of the Helmholtz equation the second fundamental problem for the infinite plane with a circular hole are solved explicitly.

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## **1 Introduction**

In the past half century, the mathematical models of multi-porosity media, as originally developed for the mechanics of naturally fractured reservoirs, have found applications in many branches of civil engineering, geotechnical engineering, technology and, in recent years, biomechanics [1-5]. Significant progress has been made towards understanding and modeling of flow processes in fractured rock. However, fractured rock may be considered as a multiporous medium but the most studies have focused naturally fractured reservoirs with double and triple porosities [6-11].

The triple porosity model represents a new possibility for the study of important problems of engineering and mechanics. The intended applications of the theories of elasticity and thermoelasticity for materials with a triple porosity structure are to geological materials such as oil and gas

reservoirs, rocks and soils, manufactured porous materials such as ceramics and pressed powders, and biomaterials such as bone [12, 4].

It should be noted that all the papers mentioned above dealt with a classical (symmetric) medium. We consider the problem of elasticity for solids with triple-porosity in the case of an elastic Cosserat medium [13].

## 2 Basic three-dimensional relations

Let an elastic body with triple-porosity occupy the domain  $\bar{\Omega} \subset R^3$ . Denote by  $(x_1, x_2, x_3)$  a point of the domain  $\bar{\Omega}$  in the Cartesian coordinate system. Let the domain  $\bar{\Omega}$  be filled with an elastic Cosserat medium having triple-porosity. The considered solid body is characterized by the displacement vector  $\mathbf{u} = (u_1, u_2, u_3)$ , rotation vector  $\boldsymbol{\omega}(\omega_1, \omega_2, \omega_3)$  and also by the fluid pressures  $p_1(x_1, x_2, x_3)$ ,  $p_2(x_1, x_2, x_3)$  and  $p_3(x_1, x_2, x_3)$  occurring respectively in the pores and fissures of the porous medium.

Then a homogeneous system of static equilibrium equations is written in the form [14, 16]

$$\begin{cases} \partial_i \sigma_{ij} = 0, \\ \partial_i \mu_{ij} + \epsilon_{jik} \sigma_{ik} = 0, \quad j = 1, 2, 3 \end{cases} \quad \text{in } \Omega, \quad (1)$$

where  $\sigma_{ij}$  are stress tensor components,  $\mu_{ij}$  are moment stress tensor components,  $\epsilon_{jik}$  is the Levi-Civita symbol,  $\partial_i \equiv \frac{\partial}{\partial x_i}$ , the summation over the recurring index  $i$  is assumed to be done from 1 to 3.

Formulas that interrelate the stress and moment stress components, the displacement and rotation vector components and the pressures  $p_1, p_2, p_3$  have the form

$$\begin{aligned} \sigma_{ij} &= (\lambda \operatorname{div} \mathbf{u} - \beta_1 p_1 - \beta_2 p_2 - \beta_3 p_3) \delta_{ij} + (\mu + \alpha) \partial_i u_j \\ &\quad + (\mu - \alpha) \partial_j u_i - 2\alpha \epsilon_{ijk} \omega_k, \\ \mu_{ij} &= \sigma \operatorname{div} \boldsymbol{\omega} \delta_{ij} + (\nu + \beta) \partial_i \omega_j + (\nu - \beta) \partial_j \omega_i, \quad j = 1, 2, 3, \end{aligned} \quad (2)$$

where  $\lambda$  and  $\mu$  are the Lam parameters,  $\alpha, \beta, \nu, \sigma$  are the constants characterizing the microstructure of the considered elastic medium,  $\beta_1, \beta_2$  and  $\beta_3$  are the effective stress parameters,  $\delta_{ij}$  is the Kronecker delta.

In the stationary case, the values  $p_1, p_2$  and  $p_3$  satisfy the following system of equations

$$\begin{cases} a_1 \Delta p_1 + a_{12}(p_2 - p_1) + a_{13}(p_3 - p_1) = 0, \\ a_2 \Delta p_2 + a_{21}(p_1 - p_2) + a_{23}(p_3 - p_2) = 0, \\ a_3 \Delta p_3 + a_{31}(p_1 - p_3) + a_{32}(p_2 - p_3) = 0, \end{cases} \quad (3)$$

where  $a_{ij}$  is the fluid transfer rate between phase  $i$  and phase  $j$ ,  $a_1 = \frac{\kappa_1}{\mu'}$ ,  $a_2 = \frac{\kappa_2}{\mu'}$ ,  $a_3 = \frac{\kappa_3}{\mu'}$ , (for the fluid phase, each phase  $i$  carries its respectively

permeability  $\kappa_i$ ),  $\mu'$  is fluid viscosity,  $\Delta \equiv \partial_{11} + \partial_{22} + \partial_{33}$  is the three-dimensional Laplace operator.

The three-dimensional system of equations (1), (2) and (3) describes the static equilibrium of a porous elastic Cosserat medium with triple-porosity. Substituting relations (2) into (1), we obtain equilibrium equations with respect to the components of the displacement and rotation vectors

$$\begin{cases} (\mu + \alpha)\Delta u_j + (\lambda + \mu - \alpha)\partial_j(\partial_k u_k) - 2\alpha \in_{ijk} \partial_i \omega_k \\ -\partial_j(\beta_1 p_1 + \beta_2 p_2 + \beta_3 p_3) = 0, \\ (\nu + \beta)\Delta \omega_j + (\sigma + \nu - \beta)\partial_j(\partial_k \omega_k) + 2\alpha \in_{jik} \partial_i u_k \\ -4\alpha \omega_j = 0, \quad j = 1, 2, 3 \end{cases} \quad \text{in } \Omega,$$

If to the system of equilibrium equations we add boundary conditions on the boundary  $\partial\Omega$  of the domain  $\Omega$ , then we can consider various classical boundary value problems.

### 3 The plane deformation case

From the basic three-dimensional equations we obtain the basic equations for the case of plane deformation. Let  $\Omega$  be a sufficiently long cylindrical body with generatrix parallel to the  $Ox_3$ -axis. Denote by  $V$  the crosssection of this cylindrical body, thus  $V \subset R^2$ . In the case of plane deformation  $u_3 = 0$ ,  $\omega_1 = 0$ ,  $\omega_2 = 0$ , while the functions  $u_1$ ,  $u_2$ ,  $\omega_3$ ,  $p_1$ ,  $p_2$  and  $p_3$  do not depend on the coordinate  $x_3$  [17].

As follows from formulas (2), in the case of plane deformation

$$\sigma_{\alpha 3} = 0, \quad \sigma_{3\alpha} = 0, \quad \mu_{\alpha\beta} = 0, \quad \mu_{33} = 0, \quad \alpha, \beta = 1, 2.$$

Therefore the system of equilibrium equations (1) takes the form

$$\begin{cases} \partial_1 \sigma_{11} + \partial_2 \sigma_{21} = 0, \\ \partial_1 \sigma_{12} + \partial_2 \sigma_{22} = 0, \\ \partial_1 \mu_{13} + \partial_2 \mu_{23} + (\sigma_{12} - \sigma_{21}) = 0, \end{cases} \quad \text{in } V, \quad (4)$$

Relations (2) are rewritten as

$$\begin{aligned} \sigma_{11} &= \lambda\theta + 2\mu\partial_1 u_1 - \beta_1 p_1 - \beta_2 p_2 - \beta_3 p_3, \\ \sigma_{22} &= \lambda\theta + 2\mu\partial_2 u_2 - \beta_1 p_1 - \beta_2 p_2 - \beta_3 p_3, \\ \sigma_{12} &= (\mu + \alpha)\partial_1 u_2 + (\mu - \alpha)\partial_2 u_1 - 2\alpha\omega_3, \\ \sigma_{21} &= (\mu + \alpha)\partial_2 u_1 + (\mu - \alpha)\partial_1 u_2 + 2\alpha\omega_3, \\ \sigma_{33} &= \lambda\theta - \beta_1 p_1 - \beta_2 p_2 - \beta_3 p_3, \\ \mu_{13} &= (\nu + \beta)\partial_1 \omega_3, \quad \mu_{23} = (\nu + \beta)\partial_2 \omega_3, \\ \mu_{31} &= (\nu - \beta)\partial_1 \omega_3, \quad \mu_{32} = (\nu - \beta)\partial_2 \omega_3, \end{aligned} \quad (5)$$

where  $\theta = \partial_1 u_1 + \partial_2 u_2$ .

Equations (3) take the form

$$\begin{cases} a_1 \Delta_2 p_1 + a_{12}(p_2 - p_1) + a_{13}(p_3 - p_1) = 0, \\ a_2 \Delta_2 p_2 + a_{21}(p_1 - p_2) + a_{23}(p_3 - p_2) = 0, \\ a_3 \Delta_2 p_3 + a_{31}(p_1 - p_3) + a_{32}(p_2 - p_3) = 0, \end{cases} \quad (6)$$

where  $\Delta_2 = \partial_{11} + \partial_{22}$  is the Laplace operator in two dimensions.

If relations (5) are substituted into system (4), then we obtain the following system of equilibrium equations with respect to the functions  $u_1$ ,  $u_2$  and  $\omega_3$

$$\begin{cases} (\mu + \alpha) \Delta_2 u_1 + (\lambda + \mu - \alpha) \partial_1 \theta + 2\alpha \partial_2 \omega_3 \\ -\partial_1 (\beta_1 p_1 + \beta_1 p_3 + \beta_1 p_3) = 0, \\ (\mu + \alpha) \Delta_2 u_2 + (\lambda + \mu - \alpha) \partial_2 \theta + 2\alpha \partial_1 \omega_3 \\ -\partial_2 (\beta_1 p_1 + \beta_1 p_3 + \beta_1 p_3) = 0, \\ (\nu + \beta) \Delta_2 \omega + 2\alpha (\partial_1 u_2 - \partial_2 u_1) - 4\alpha \omega_3 = 0, \end{cases} \quad \text{in } V, \quad (7)$$

On the plane  $Ox_1x_2$ , we introduce the complex variable  $z = x_1 + ix_2 = re^{i\theta}$ , ( $i^2 = -1$ ) and the operators  $\partial_z = 0.5(\partial_1 - i\partial_2)$ ,  $\partial_{\bar{z}} = 0.5(\partial_1 + i\partial_2)$ ,  $\bar{z} = x_1 - ix_2$ , and  $\Delta_2 = 4\partial_z\partial_{\bar{z}}$ .

To write system (4) in the complex form, the second equation of this system is multiplied by  $i$  and summed up with the first equation

$$\begin{cases} \partial_z (\sigma_{11} - \sigma_{22} + i(\sigma_{12} + \sigma_{21})) + \partial_{\bar{z}} (\sigma_{11} + \sigma_{22} + i(\sigma_{12} - \sigma_{21})) = 0, \\ \partial_z (\mu_{13} + i\mu_{23}) + \partial_{\bar{z}} (\mu_{13} - i\mu_{23}) + \sigma_{12} - \sigma_{21} = 0, \end{cases} \quad (8)$$

where by formulas (5)

$$\begin{aligned} \sigma_{11} - \sigma_{22} + i(\sigma_{12} + \sigma_{21}) &= 4\mu \partial_{\bar{z}} u_+, \\ \sigma_{11} + \sigma_{22} + i(\sigma_{12} - \sigma_{21}) &= 2(\lambda + \mu - \alpha)\theta + 4\alpha \partial_z u_+ - 4\alpha i \omega_3 \\ -2(\beta_1 p_1 + \beta_2 p_2 + \beta_3 p_3), \\ \mu_{13} + i\mu_{23} &= 2(\nu + \beta) \partial_{\bar{z}} \omega_3, \quad \mu_{31} + i\mu_{32} = 2(\nu - \beta) \partial_{\bar{z}} \omega_3, \end{aligned} \quad (9)$$

$$u_+ = u_1 + iu_2, \quad \theta = \partial_z u_+ + \partial_{\bar{z}} \bar{u}_+.$$

We write equations (6)

$$\Delta_2 p - Ap = 0, \quad A = \begin{pmatrix} b_1/a_1 & -a_{12}/a_1 & -a_{13}/a_1 \\ -a_{21}/a_2 & b_2/a_2 & -a_{23}/a_2 \\ -a_{31}/a_3 & -a_{32}/a_3 & b_3/a_3 \end{pmatrix} \quad (10)$$

$$p = (p_1, p_2, p_3)^T,$$

$$b_1 = a_{12} + a_{13}, \quad b_2 = a_{21} + a_{23}, \quad b_3 = a_{31} + a_{32}.$$

If relations (9) are substituted into system (8), then system (7) is written in the complex form

$$\begin{cases} 2(\mu + \alpha)\partial_{\bar{z}}\partial_z u_+ + (\lambda + \mu - \alpha)\partial_{\bar{z}}\theta - 2\alpha i\partial_{\bar{z}}\omega_3 \\ -\partial_{\bar{z}}(\beta_1 p_1 + \beta_2 p_2 + \beta_3 p_3) = 0, \\ 2(\nu + \beta)\partial_{\bar{z}}\partial_z \omega_3 + \alpha i(\theta - 2\partial_z u_+) - 2\alpha\omega_3 = 0, \end{cases} \quad \text{in } V. \quad (11)$$

#### 4 The general solution of system (10-11)

In this section, we construct the analogues of the Kolosov-Muskhelishvili formulas [17] for system (10-11).

Equations (10) imply that

$$\begin{aligned} p_1 &= f'(z) + \overline{f'(z)} + l_{11}\chi_1(z, \bar{z}) + l_{12}\chi_2(z, \bar{z}), \\ p_2 &= f'(z) + \overline{f'(z)} + l_{21}\chi_1(z, \bar{z}) + l_{22}\chi_2(z, \bar{z}), \\ p_3 &= f'(z) + \overline{f'(z)} + l_{31}\chi_1(z, \bar{z}) + l_{32}\chi_2(z, \bar{z}), \end{aligned} \quad (12)$$

where  $f(z)$  is an arbitrary analytic functions of a complex variable  $z$  in the domain  $V$  and  $\chi_\alpha(z, \bar{z})$  is an arbitrary solution of the Helmholtz equation

$$\Delta_2 \chi_\alpha(z, \bar{z}) - \kappa_\alpha \chi_\alpha(z, \bar{z}) = 0,$$

$\kappa_\alpha$  are eigenvalues and  $(l_{11}, l_{21}, l_{31}), (l_{12}, l_{22}, l_{32})$  are eigenvectors of the matrix  $A$ .

**Theorem.** *The general solution of the system of equations (12) is represented as follows:*

$$\begin{aligned} 2\mu u_+ &= \varkappa\varphi(z) - z\overline{\varphi'(z)} - \overline{\psi(z)} + \frac{\mu(\beta_1 + \beta_2 + \beta_3)}{\lambda + 2\mu}(f(z) + z\overline{f'(z)}) \\ &\quad + 2i\partial_{\bar{z}}\tau(z, \bar{z}) + \frac{4\mu}{\lambda + 2\mu}\partial_{\bar{z}}[\delta_1\chi_1(z, \bar{z}) + \delta_2\chi_2(z, \bar{z})], \\ 2\mu\omega_3 &= \frac{2\mu}{\nu + \beta}\tau(z, \bar{z}) - \frac{\varkappa + 1}{2}i(\varphi'(z) - \overline{\varphi'(z)}), \end{aligned} \quad (13)$$

where  $\varkappa = \frac{\lambda + 3\mu}{\lambda + \mu}$ ,  $\delta_\alpha := \frac{l_{1\alpha}}{\kappa_\alpha}\beta_1 + \frac{l_{2\alpha}}{\kappa_\alpha}\beta_2 + \frac{l_{3\alpha}}{\kappa_\alpha}\beta_3$ ,  $\varphi(z)$  and  $\psi(z)$  are arbitrary analytic functions of a complex variable  $z$  in the domain  $V$ ,  $\chi(z, \bar{z})$  is an arbitrary solution of the Helmholtz equation

$$\Delta_2 \tau(z, \bar{z}) - \xi^2 \tau(z, \bar{z}) = 0,$$

where

$$\xi^2 := \frac{4\mu\alpha}{(\nu + \beta)(\mu + \alpha)} > 0.$$

**Proof.** We take the operator  $\partial_{\bar{z}}$  out of the brackets in the left-hand part of the first equation of system (11)

$$\begin{aligned} &\partial_{\bar{z}}(2(\mu + \alpha)\partial_z u_+ + (\lambda + \mu - \alpha)\theta - 2\alpha i\omega_3 \\ &- (\beta_1 p_1 + \beta_2 p_2 + \beta_3 p_3)) = 0. \end{aligned} \tag{14}$$

Since (14) is a system of Cauchy-Riemann equations, we have

$$\begin{aligned} &2(\mu + \alpha)\partial_z u_+ + (\lambda + \mu - \alpha)\theta - 2\alpha i\omega_3 \\ &= (\varkappa + 1)\varphi'(z) + \beta_1 p_1 + \beta_2 p_2 + \beta_3 p_3, \end{aligned} \tag{15}$$

where  $\varphi(z)$  is an arbitrary analytic function of  $z$ .

A conjugate equation to (15) has the form

$$\begin{aligned} &2(\mu + \alpha)\partial_{\bar{z}} \bar{u}_+ + (\lambda + \mu - \alpha)\theta + 2\alpha i\omega_3 \\ &= (\varkappa + 1)\overline{\varphi'(z)} + \beta_1 p_1 + \beta_2 p_2 + \beta_3 p_3, \end{aligned} \tag{16}$$

Summing up equations (15) and (16) and taking into account that

$$\theta = \partial_z u_+ + \partial_{\bar{z}} \bar{u}_+,$$

we obtain

$$\theta = \frac{1}{\lambda + \mu}(\varphi'(z) + \overline{\varphi'(z)}) + \frac{1}{\lambda + 2\mu}(\beta_1 p_1 + \beta_2 p_2 + \beta_3 p_3). \tag{17}$$

If from equation (15) we subtract equation (16) and write the expression  $i(\partial_z u_+ - \partial_{\bar{z}} \bar{u}_+)$ , then we have

$$i(\partial_z u_+ - \partial_{\bar{z}} \bar{u}_+) = \frac{\varkappa + 1}{2(\mu + \alpha)}i(\varphi'(z) - \overline{\varphi'(z)}) - \frac{2\alpha}{\mu + \alpha}\omega_3. \tag{18}$$

The second equation of system (11) is written as

$$4\partial_z \partial_{\bar{z}} \omega_3 - \frac{2\alpha}{\nu + \beta}i(\partial_z u_+ - \partial_{\bar{z}} \bar{u}_+)\omega_3 - \frac{4\alpha}{\nu + \beta}\omega_3 = 0. \tag{19}$$

Substituting formula (18) into formula (19) we obtain the equation

$$\Delta_2 \omega_3 - \xi^2 \omega_3 = \frac{\alpha(\varkappa + 1)}{(\nu + \beta)(\mu + \alpha)}i(\varphi'(z) - \overline{\varphi'(z)}). \tag{20}$$

The general solution of equation (20) is written in the form

$$2\mu\omega_3 = \frac{2\mu}{\nu + \beta}\tau(z, \bar{z}) - \frac{\varkappa + 1}{2}i(\varphi'(z) - \overline{\varphi'(z)}), \tag{21}$$

where  $\tau(z, \bar{z})$  is a general solution of the Helmholtz equation

$$\Delta_\tau - \xi^2 \tau = 0. \quad (22)$$

The multiplier  $\frac{2\mu}{\nu + \beta}$  has been introduced for convenience in writing our subsequent formulas.

Substituting formulas (17) and (21) into equation (16) and taking into account that  $\tau(z, \bar{z})$  is a solution of equation (22), we obtain

$$\begin{aligned} 2\mu \partial_z u_+ &= \varkappa \varphi'(z) - \overline{\varphi'(z)} + 2i \partial_z \partial_{\bar{z}} \tau(z, \bar{z}) \\ &+ \frac{\mu}{\lambda + 2\mu} (\beta_1 p_1 + \beta_2 p_2 + \beta_3 p_3). \end{aligned} \quad (23)$$

From formulas (12) we find the following expression for the combination  $\beta_1 p_1 + \beta_2 p_2 + \beta_3 p_3$

$$\beta_1 p_1 + \beta_2 p_2 + \beta_3 p_3 = (\beta_1 + \beta_2 + \beta_3) (f'(z) + \overline{f'(z)}) + 4 \partial_z \partial_{\bar{z}} [\delta_1 \chi_1(z, \bar{z}) + \delta_2 \chi_2(z, \bar{z})].$$

Substituting the latter formula into (23), integrating over  $z$  we obtain formula (13) which we are proving.

Substituting expressions (13) and (14) into formulas (9), for combinations of stress tensor components we obtain the following formulas

$$\begin{aligned} &\sigma_{11} + \sigma_{22} + i(\sigma_{12} - \sigma_{21}) \\ &= 2 \left[ \varphi'(z) + \overline{\varphi'(z)} - 2i \partial_z \partial_{\bar{z}} \tau - \frac{\mu(\beta_1 + \beta_2 + \beta_3)}{\lambda + 2\mu} (f'(z) + \overline{f'(z)}) \right] \\ &\quad - \frac{8\mu}{\lambda + 2\mu} \partial_z \partial_{\bar{z}} [\delta_1 \chi_1(z, \bar{z}) + \delta_2 \chi_2(z, \bar{z})], \\ &\sigma_{11} - \sigma_{22} + i(\sigma_{12} + \sigma_{21}) = 2 \left[ -z \overline{\varphi''(z)} - \overline{\psi'(z)} + 2i \partial_z \partial_{\bar{z}} \tau \right] \\ &\quad + \frac{2\mu(\beta_1 + \beta_2 + \beta_3)}{\lambda + 2\mu} z \overline{f''(z)} + \frac{8\mu}{\lambda + 2\mu} \partial_z \partial_{\bar{z}} [\delta_1 \chi_1(z, \bar{z}) + \delta_2 \chi_2(z, \bar{z})], \\ &\sigma_{33} = \frac{\lambda}{\lambda + \mu} \left[ \varphi'(z) + \overline{\varphi'(z)} \right] - \frac{8\mu}{\lambda + 2\mu} \partial_z \partial_{\bar{z}} [\delta_1 \chi_1(z, \bar{z}) + \delta_2 \chi_2(z, \bar{z})] \\ &\quad - \frac{2\mu}{\lambda + 2\mu} (\beta_1 + \beta_2 + \beta_3) (f'(z) + \overline{f'(z)}), \\ &\mu_{13} + i\mu_{23} = 2 \partial_{\bar{z}} \tau + \frac{(\varkappa + 1)(\nu + \beta)}{2\mu} i \overline{\varphi''(z)}, \\ &\mu_{31} + i\mu_{32} = \frac{2(\nu - \beta)}{\nu + \beta} \partial_{\bar{z}} \tau + \frac{(\varkappa + 1)(\nu - \beta)}{2\mu} i \overline{\varphi''(z)}. \end{aligned}$$

Thus, the general solution of a two-dimensional system of differential equations that describes the static equilibrium of a porous elastic medium

with triple-porosity is represented by means of three analytic functions of a complex variable and three solutions of the Helmholtz equation. By an appropriate choice of these functions we can satisfy five independent classical boundary conditions.

Let mutually perpendicular unit vectors  $\mathbf{l}$  and  $\mathbf{s}$  be such that

$$\mathbf{l} \times \mathbf{s} = \mathbf{e}_3,$$

where  $\mathbf{e}_3$  is the unit vector directed along the  $x_3$ -axis. The vector  $\mathbf{l}$  forms the angle  $\vartheta$  with the positive direction of the  $x_1$ -axis. Then the displacement components  $u_l = \mathbf{u} \cdot \mathbf{l}$ ,  $u_s = \mathbf{u} \cdot \mathbf{s}$  as well as the stress and moment stress components acting on an area of arbitrary orientation are expressed by the formulas

$$\begin{aligned} u_l + iu_s &= e^{-i\vartheta} u_+, \\ \sigma_{ll} + i\sigma_{ls} &= \frac{1}{2} \left[ \sigma_{11} + \sigma_{22} + i(\sigma_{12} - \sigma_{21}) \right. \\ &\quad \left. + (\sigma_{11} - \sigma_{22} + i(\sigma_{12} + \sigma_{21})) e^{-2i\vartheta} \right], \\ \mu_{l3} &= \frac{1}{2} \left[ (\mu_{13} + i\mu_{23}) e^{-i\vartheta} + (\mu_{13} - i\mu_{23}) e^{i\vartheta} \right]. \end{aligned}$$

## 5 Solution of the second fundamental problem for the infinite plane with a circular hole

Let the origin of coordinates be at the centre of the hole of radius  $R$ .

On the boundary of the considered domain the values of pressures  $p_1$ ,  $p_2$ ,  $p_3$ , the displacement and rotation vectors are given.

We consider the following problem

$$p_j|_{r=R} = P_j = \sum_{-\infty}^{+\infty} A_{nj} e^{in\vartheta}, \quad A_{nj} = \overline{A_{-nj}}, \quad j = \overline{1, 3}, \quad (24)$$

$$\begin{aligned} 2\mu u_+|_{r=R} &= 2\mu(G_1 + iG_2) = \sum_{-\infty}^{+\infty} B_n e^{in\vartheta}, \\ 2\mu\omega_3|_{r=R} &= 2\mu G_3 = \sum_{-\infty}^{+\infty} C_n e^{in\vartheta}, \quad C_n = \overline{C_{-n}}. \end{aligned} \quad (25)$$

The analytic function  $f'(z)$  and the metaharmonic functions  $\chi_\alpha(z, \bar{z})$  is represented as a series

$$f'(z) = \sum_{n=0}^{\infty} a_n z^{-n}, \quad \chi_\alpha(z, \bar{z}) = \sum_{-\infty}^{+\infty} \alpha_{n\alpha} K_n(\kappa_\alpha r) e^{in\vartheta},$$



where  $K_n(\cdot)$  is modified Bessel function of  $n$ -th order, and are substituted in the boundary conditions (24) we have

$$\sum_{n=0}^{\infty} \left( \frac{a_n}{R^n} e^{-in\vartheta} + \frac{\bar{a}_n}{R^n} e^{in\vartheta} \right) + \sum_{-\infty}^{+\infty} [l_{j1}\alpha_{n1}K_n(\kappa_1R) + l_{j2}\alpha_{n2}K_n(\kappa_2R)]e^{in\vartheta} = \sum_{-\infty}^{+\infty} A_{nj}e^{in\vartheta},$$

Compare the coefficients at identical degrees. We obtain the following systems of equations

$$\begin{aligned} a_0 + \bar{a}_0 + l_{j1}K_0(\kappa_1R)\alpha_{01} + l_{j2}K_0(\kappa_2R)\alpha_{02} &= A_{0j}, \quad j = 1, 2, 3, \\ \frac{1}{R^n}\bar{a}_n + l_{j1}K_n(\kappa_1R)\alpha_{n1} + l_{j2}K_n(\kappa_2R)\alpha_{n2} &= A_{nj}, \quad j = 1, 2, 3. \end{aligned} \quad (26)$$

It is also assumed that  $a_0$  is a real value; that is,  $a_0 = \bar{a}_0$ . The coefficients  $a_n$ ,  $\alpha_{n1}$ ,  $\alpha_{n2}$ , are found by solving (26).

The analytic functions  $\varphi(z)$ ,  $\psi(z)$  and the metaharmonic functions  $\tau(z, \bar{z})$  are represented as series

$$\varphi'(z) = \sum_{n=0}^{\infty} b_n z^{-n}, \quad \psi'(z) = \sum_{n=0}^{\infty} c_n z^{-n}, \quad \tau(z, \bar{z}) = \sum_{-\infty}^{+\infty} \alpha_n K_n(\xi r) e^{in\vartheta}$$

and are substituted in the boundary conditions (25) we have

$$\begin{aligned} & \varkappa \left( R b_0 e^{i\vartheta} + \ln R b_1 + b_1 i\vartheta - \sum_{n=2}^{\infty} \frac{b_n e^{i(1-n)\vartheta}}{(n-1)R^{n-1}} \right) \\ & - \sum_{n=0}^{\infty} \frac{\bar{b}_n}{R^{n-1}} e^{i(n+1)\vartheta} - R \bar{c}_0 e^{-i\vartheta} - \ln R \bar{c}_1 + \bar{c}_1 i\vartheta \\ & + \sum_{n=2}^{\infty} \frac{\bar{c}_n e^{i(n-1)\vartheta}}{(n-1)R^{n-1}} - i\xi \sum_{-\infty}^{\infty} \alpha_n K_{n+1}(\xi R) e^{i(n+1)\vartheta} \\ & + \frac{\mu(\beta_1 + \beta_2 + \beta_3)}{\lambda + 2\mu} \left[ \ln R a_1 + i\vartheta a_1 - \sum_{n=2}^{\infty} \frac{a_n}{(n-1)R^{n-1}} e^{i(1-n)\vartheta} \right. \\ & \left. + (a_0 + \bar{a}_0) R e^{i\vartheta} + \sum_{n=1}^{\infty} \frac{\bar{a}_n}{R^{n-1}} e^{i(n+1)\vartheta} \right] - \frac{4\mu}{\lambda + 2\mu} \\ & \times \sum_{-\infty}^{+\infty} \left( \frac{\delta_1 \kappa_1}{2} K_{n+1}(\kappa_1 R) \alpha_{n1} + \frac{\delta_2 \kappa_2}{2} K_{n+1}(\kappa_2 R) \alpha_{n2} \right) e^{i(n+1)\vartheta} \\ & = \sum_{-\infty}^{+\infty} B_n e^{in\vartheta}, \end{aligned} \quad (27)$$

$$\begin{aligned} & \frac{2\mu}{\nu + \beta} \sum_{-\infty}^{+\infty} \alpha_n K_n(\xi R) e^{in\vartheta} + \frac{\varkappa + 1}{2} i \sum_{n=0}^{\infty} \left( \frac{a_n}{R^n} e^{-in\vartheta} - \frac{\bar{a}_n}{R^n} e^{in\vartheta} \right) \\ & = \sum_{-\infty}^{+\infty} C_n e^{in\vartheta}. \end{aligned} \tag{28}$$

Compare the coefficients at identical degrees. Then one obtains from the constant term and from those involving  $e^{i\vartheta}$ ,  $e^{-i\vartheta}$  and  $e^{2i\vartheta}$  respectively

$$\begin{cases} \varkappa \ln R \bar{b}_1 - \ln R c_1 + i\xi K_0(\xi R) \alpha_1 = \bar{B}'_0, \\ \frac{(\varkappa + 1)i}{2R} \bar{b}_1 + \frac{2\mu}{\nu + \beta} K_1(\xi R) \alpha_1 = C_1, \end{cases} \tag{29}$$

$$\begin{cases} \varkappa R b_0 - R \bar{b}_0 + \frac{1}{R} \bar{c}_2 - i\xi K_1(\xi R) \alpha_0 = \bar{B}'_1, \\ \frac{(\varkappa + 1)i}{2} (\bar{b}_0 - b_0) + \frac{2\mu}{\nu + \beta} K_0(\xi R) \alpha_0 = C_0, \end{cases} \tag{30}$$

$$\begin{cases} -\frac{\varkappa}{R} b_2 - R \bar{c}_0 - i\xi K_{-1}(\xi R) \alpha_{-2} = B'_{-1}, \\ \frac{(\varkappa + 1)i}{2R^2} \bar{b}_2 + \frac{2\mu}{\nu + \beta} K_2(\xi R) \alpha_2 = C_2, \end{cases} \tag{31}$$

where

$$\begin{aligned} B'_0 &= B_0 - \frac{\mu(\beta_1 + \beta_2 + \beta_3) \ln R}{\lambda + 2\mu} a_1 \\ &+ \frac{4\mu}{\lambda + 2\mu} \left( \frac{\delta_1 \kappa_1}{2} K_0(\kappa_1 R) \alpha_{-11} + \frac{\delta_2 \kappa_2}{2} K_0(\kappa_2 R) \alpha_{-12} \right), \\ B'_1 &= B_1 - \frac{\mu(\beta_1 + \beta_2 + \beta_3) R}{\lambda + 2\mu} (a_0 + \bar{a}_0) \\ &+ \frac{4\mu}{\lambda + 2\mu} \left( \frac{\delta_1 \kappa_1}{2} K_1(\kappa_1 R) \alpha_{01} + \frac{\delta_2 \kappa_2}{2} K_1(\kappa_2 R) \alpha_{02} \right), \\ B'_{-1} &= B_{-1} + \frac{\mu(\beta_1 + \beta_2 + \beta_3)}{(\lambda + 2\mu) R} a_2 \\ &+ \frac{4\mu}{\lambda + 2\mu} \left( \frac{\delta_1 \kappa_1}{2} K_{-1}(\kappa_1 R) \alpha_{-21} + \frac{\delta_2 \kappa_2}{2} K_{-1}(\kappa_2 R) \alpha_{-22} \right). \end{aligned}$$

For  $e^{in\vartheta}$  ( $n = \pm 2, \pm 3, \dots$ ) gives

$$\begin{aligned} & -\frac{\varkappa}{(n-1)R^{n-1}} \bar{b}_n + i\xi K_{n-1}(\xi R) \alpha_n = \bar{B}'_{-n+1}, \quad n \geq 3 \\ & \frac{(\varkappa + 1)i}{2R^n} \bar{b}_n + \frac{2\mu}{\nu + \beta} K_n(\xi R) \alpha_n = C_n, \quad n \geq 3 \end{aligned} \tag{32}$$

$$\frac{1}{(n-1)R^{n-1}} \bar{c}_n - \frac{1}{R^{n-3}} \bar{b}_{n-2} - i\xi K_{n-1}(\xi R) \alpha_{n-2} = B'_{n-1}, \quad n \geq 3 \tag{33}$$

where

$$\begin{aligned} B'_{-n} &= B_{-n} - \frac{\mu(\beta_1 + \beta_2 + \beta_3)}{\lambda + 2\mu} \frac{a_{n+1}}{nR^n} \\ &+ \frac{4\mu}{\lambda + 2\mu} \left( \frac{\delta_1 \kappa_1}{2} K_{-n-1}(\kappa_1 R) \alpha_{-n-11} + \frac{\delta_2 \kappa_2}{2} K_{-n-1}(\kappa_2 R) \alpha_{-n-12} \right), \\ B'_n &= B_n + \frac{\mu(\beta_1 + \beta_2 + \beta_3)}{\lambda + 2\mu} \frac{(n-2)\bar{a}_{n-1}}{R^{n-2}} \\ &+ \frac{4\mu}{\lambda + 2\mu} \left( \frac{\delta_1 \kappa_1}{2} K_n(\kappa_1 R) \alpha_{n-11} + \frac{\delta_2 \kappa_2}{2} K_n(\kappa_2 R) \alpha_{n-12} \right). \end{aligned}$$

It is known that

$$b_0 = \Gamma - \frac{\mu(\beta_1 + \beta_2 + \beta_3)}{\lambda + 2\mu} (a_0 + \bar{a}_0), \quad c_0 = \Gamma',$$

where  $\Gamma, \Gamma'$  are known quantities, specifying the stress distribution at infinity (It is also assumed that  $b_0$  is a real value (see [17])). Hence, by the formulae (30-31)

$$\begin{aligned} \alpha_0 &= \frac{\nu + \beta}{2\mu K_0(\xi R)} C_0, \quad c_2 = -R^2(\varkappa - 1)b_0 - i\xi R K_1(\xi R) \alpha_0 + R\bar{A}_1, \\ \bar{b}_2 &= 2R^2 \frac{(\nu + \beta)i\xi K_1(\xi R)C_2 - 2\mu K_2(\xi R)(\bar{A}_{-1} + Rb_0)}{4\mu R \varkappa K_2(\xi R) - (\nu + \beta)(\varkappa + 1)\xi K_1(\xi R)}, \\ \alpha_2 &= \frac{(\varkappa + 1)i(\bar{A}_{-1} + Rb_0) + 2R \varkappa C_2}{4\mu R \varkappa K_2(\xi R) - (\nu + \beta)(\varkappa + 1)\xi K_1(\xi R)} (\nu + \beta). \end{aligned}$$

In order to find expressions for  $b_1$  and  $c_1$ , it is necessary to refer to the condition for single-valuedness of the displacements

$$\varkappa b_1 + \bar{c}_1 = -\frac{\lambda(\beta_1 + \beta_2 + \beta_3)}{\lambda + 2\mu} a_1,$$

which in combination with the second relation of (29) gives

$$\begin{aligned} b_1 &= \frac{B'_0 - \frac{\lambda(\beta_1 + \beta_2 + \beta_3) \ln R}{\lambda + 2\mu} a_1 + i\xi K_0(\xi R) \bar{C}_1}{2\varkappa \ln R + \frac{(\varkappa + 1)\xi K_0(\xi R)}{2R}}, \\ c_1 &= -\varkappa \bar{b}_1 - \frac{\lambda(\beta_1 + \beta_2 + \beta_3) \ln R}{\lambda + 2\mu} \bar{a}_1, \\ \alpha_1 &= C_1 - \frac{(\varkappa + 1)i}{2R} \bar{b}_1, \end{aligned}$$

and, finally, (32-33) determines all coefficients  $b_n, c_n, \alpha_n$ :

$$b_n = \frac{\Delta_{1n}}{\Delta_n}, \quad \alpha_n = \frac{\Delta_{2n}}{\Delta_n}, \quad n > 2,$$

$$c_n = (n-1)R^{n-1} \left( \frac{b_{n-2}}{R^{n-3}} - i\xi K_{n-1}(\xi R) \bar{\alpha}_{n-2} + \bar{B}'_{n-1} \right), \quad n > 2,$$

where

$$\Delta_{1n} = -\frac{2\mu}{\nu + \beta} K_n(\xi R) B'_{1-n} - i\xi K_{n-1}(\xi R) C_{-n},$$

$$\Delta_{2n} = \frac{(\varkappa + 1)i}{2R^n} \bar{B}'_{1-n} + \frac{\varkappa}{(n-1)R^{n-1}} C_n,$$

$$\Delta_n = \frac{2\mu\varkappa K_n(\xi R)}{(\nu + \beta)(n-1)R^{n-1}} - \frac{(\varkappa + 1)\xi K_{n-1}(\xi R)}{2R^n}.$$

It is easy to prove the absolute and uniform convergence of the series obtained in the circular ring (including the contours) when the functions set on the boundaries have sufficient smoothness.

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