ON THE NUMERICAL SOLUTION OF CONTACT PROBLEM FOR POISSON'S AND KIRCHHOFF EQUATION SYSTEM

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Abstract

In this paper stress-deformed state for some "bridge-form" multystructures studied having difficult geometry. Particularly the boundary-contacted problem is considered. Two rectangle (particularly a square) form membranes are connected by a string; We consider classic linear boundary problems for membranes (Poisson's equation), but for string nonlinear Kirchhoff type integro-differential equation. The account program in MATLAB is created and numerical experiments are made.

Key words and phrases: Poisson's equation, Kirchhoff type nonlinear integrodifferential equation, finite-difference method.

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1 Introduction

The stress - deformed condition for some "bridge - form" multystructures with difficult geometry (two rectangular membranes is connected by the string, (see fig.1)) is studied using numerical methods (finite-difference methods). Membrane bending is represented by the Poisson's equation (see, for example [1]). The equation of the string by Kirchhoff type nonlinear integro-differential equation (see, for example [2]). The function of a membranes bending in central points is found by direct numerical methods, and the iterative method for definition of numerical values of function of a bend of a string for the approached decision of nonlinear equation Kirchhoff type.

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2 Statement of the Problem

It is possible to dismantle the above boundary - contact problem in three separate tasks:

a). Boundary value problem for the right membranes

$$\Delta w_1(x,y) = f_1(x,y), \ (x,y) \in \Omega_1 = \{(x,y) : a \le x \le c, \ -b \le y \le b\}, \ (2.1)$$

$$w_1(x,\pm b) = 0, \quad w_1(c,y) = 0, \quad a \le x \le c, \quad -b \le y \le b,$$
 (2.2)

$$\frac{\partial w_1(x,y)}{\partial x}\Big|_{x=a} = 0, \quad -b \le y \le b.$$
(2.3)

b). Boundary value problem for the left membranes

$$\Delta w_2(x,y) = f_2(x,y), \ (x,y) \in \Omega_2 = \{(x,y) : -c \le x \le -a, -b \le y \le b\},$$
(2.4)

$$w_2(x,\pm b) = 0, \quad w_2(-c,y) = 0, \quad -c \le x \le -a, \quad -b \le y \le b,$$
 (2.5)

$$\frac{\partial w_2(x,y)}{\partial x}\Big|_{x=-a} = 0, \quad -b \le y \le b.$$
(2.6)

c). Boundary value problem for a string

$$\left[m_0 + m_1 \int_{-a}^{+a} \left(w'_3(t)\right)^2 dt\right] w''_3(x) = f_3(x), \quad -a \le y \le a, \tag{2.7}$$

$$w_3(-a) = a_2, \quad w_3(a) = a_1,$$
 (2.8)

where $a_1 \approx w_1(a, 0)$, $a_2 \approx w_2(-a, 0)$, $m_0, m_1 > 0$.

3 The Algorithm

In order to solve of this boundary value problem we use the finite - difference method. Let's consider the case of the square is c - a = 2b; Ω_1 and Ω_2 squares to make a regular square grid step $h_1 = h_2 = h$, $(n_1 = n_2 = n)$,

$$h_1 = \frac{c-a}{n_1} = h_2 = \frac{2b}{n_2} = h, \ x_i = a + ih_1, \ i = 0, 1, 2, \cdots, n_1$$

or

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$$x_i = -c + ih_1, i = 0, 1, 2, \cdots, n_1, \quad y_j = -b + jh_2, j = 0, 1, 2, \cdots, n_2.$$

The part of a string [-a, a] section is divided $2n_3$ by step h_3 ,

$$h_3 = a/n_3, \ x_i = -a + ih_3, \ i = 0, 1, 2, \cdots, 2n_3.$$

Let's replace differential operators the finite - difference analog. It is changed (2.1), (2.4) equations of the second order differential operators by the template difference five point margin of error $O(h^2)$;

Let's replace the first order differential operators (2.3), (2.6) by method A: two-point template to change the error O(h) and by method B: three - point template to change the error $O(h^2)$.

Let's change (2.7) a string equation lookup function by the $O(h_3^2)$ - order derivatives of the second order derivative by the three - point template.

In order to solve of this given nonlinear difference problem we use the iterative method.

Let's accept following marking for grid functions

$$\begin{split} w_{1,i,j} &\equiv w \mathbf{1}_{i,j} \approx w_1(x_i, y_j), \, w_{2,i,j} \equiv w \mathbf{2}_{i,j} \approx w_2(x_i, y_j), \, w_{3,i} \equiv w \mathbf{3}_i \approx w_3(x_i), \\ f_{1,i,j} &\equiv f \mathbf{1}_{i,j} \approx f_1(x_i, y_j), \, f_{2,i,j} \equiv f \mathbf{2}_{i,j} = f_2(x_i, y_j), \, f_{3,i} \equiv f \mathbf{3}_i = f_3(x_i). \end{split}$$

Method A. In case of (2.1)-(2.3) problem we have will the task of following a tree - block diagonal system of equation

1	A	E	Θ	Θ	·	·	·	Θ	Θ	 (W1,1)		(F1,1)
	E	B	E	Θ	•	•	•	Θ	Θ	W1,2		F1,2
	Θ	E	B	E	Θ	•	•	Θ	Θ	W1,3		F1, 3
	Θ	Θ	E	B	E	Θ	•	Θ	Θ	W1, 4		F1, 4
	•	•	•	•	•	•	•	•	•	•	=	
	•	•	•	•	•	•	•	•	•			
	Θ	Θ	•	•	Θ	E	B	E	Θ	W1, n - 3		F1, n-3
	Θ	Θ	•	•	•	Θ	E	B	E	W1, n - 2		F1, n-2
	Θ	Θ	Θ	•			Θ	E	B /	$V_{1,n-1}$		$\setminus F1, n-1$

and in case of (2.4) - (2.6) problem we will have follow task

1	B	E	Θ	Θ	•	•	•	Θ	Θ	(W2,1)		(F2,1)	
l	E	B	E	Θ	•	•	•	Θ	Θ	W2,2		F2,2	
l	Θ	E	B	E	Θ	•	•	Θ	Θ	W2, 3		F2,3	
	Θ	Θ	E	B	E	Θ	•	Θ	Θ	W2, 4		F2, 4	
	•	•	•	•	•	•	•	•	•		=		,
	•	•	•	•	•	•	•	•	•				
	Θ	Θ	•	•	Θ	E	B	E	Θ	W2, n - 3		F2, n - 3	
l	Θ	Θ	•	•	•	Θ	E	B	E	W2, n-2		F2, n-2	
	Θ	Θ	Θ	•	•	•	Θ	E	A	$V_{2,n-1}$		$\setminus F2, n-1$ /	/

where

$$A = \begin{pmatrix} -3 & 1 & 0 & 0 & \cdots & \cdots & 0 & 0 \\ 1 & -3 & 1 & 0 & \cdots & \cdots & 0 & 0 \\ 0 & 1 & -3 & 1 & 0 & \cdots & 0 & 0 \\ 0 & 0 & 1 & -3 & 1 & 0 & \cdots & 0 & 0 \\ \vdots & \vdots \\ 0 & 0 & \vdots & \vdots & 0 & 1 & -3 & 1 & 0 \\ 0 & 0 & \vdots & \vdots & 0 & 1 & -3 & 1 \\ 0 & 0 & 0 & \vdots & \vdots & 0 & 1 & -3 & 1 \\ 0 & 0 & 0 & \vdots & \vdots & 0 & 0 & 1 \\ 0 & 0 & 0 & \vdots & \vdots & 0 & 0 & 0 \\ \vdots & \vdots \\ 0 & 0 & 1 & -4 & 1 & 0 & \vdots & 0 & 0 \\ 0 & 1 & -4 & 1 & 0 & \vdots & \vdots & 0 & 0 \\ 0 & 0 & 1 & -4 & 1 & 0 & \vdots & 0 & 0 \\ \vdots & \vdots \\ 0 & 0 & 0 & \vdots & \vdots & 0 & 1 & -4 & 1 \\ 0 & 0 & 0 & \vdots & \vdots & 0 & 1 & -4 & 1 \\ 0 & 0 & 0 & \vdots & \vdots & 0 & 0 & 1 & -4 \end{pmatrix}$$
$$E = \begin{pmatrix} 1 & 0 & 0 & 0 & \vdots & \vdots & 0 & 0 \\ 0 & 1 & 0 & 0 & \vdots & \vdots & 0 & 0 \\ 0 & 1 & 0 & 0 & \vdots & \vdots & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & \vdots & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & \vdots & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \vdots & \vdots & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & \vdots & 0 & 0 & 1 \end{pmatrix}$$

$$W2,1=\begin{pmatrix} w2_{1,1} \\ w2_{1,2} \\ w2_{1,3} \\ w2_{1,4} \\ \vdots \\ w2_{1,n-3} \\ w2_{1,n-2} \\ w2_{1,n-1} \end{pmatrix}, W2,2=\begin{pmatrix} w2_{2,1} \\ w2_{2,2} \\ w2_{2,3} \\ w2_{2,4} \\ \vdots \\ w2_{2,n-3} \\ w2_{2,n-2} \\ w2_{2,n-1} \end{pmatrix}, \cdots, W2,n-1=\begin{pmatrix} w2_{n-1,1} \\ w2_{n-1,2} \\ w2_{n-1,3} \\ w2_{n-1,4} \\ \vdots \\ w2_{n-1,n-3} \\ w2_{n-1,n-2} \\ w2_{n-1,n-2} \\ w2_{n-1,n-1} \end{pmatrix},$$

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$$F2,1 = \begin{pmatrix} f2_{1,1} \\ f2_{1,2} \\ f2_{1,3} \\ f2_{1,4} \\ \vdots \\ f2_{1,n-3} \\ f2_{1,n-2} \\ f2_{1,n-1} \end{pmatrix}, F2,2 = \begin{pmatrix} f2_{2,1} \\ f2_{2,2} \\ f2_{2,3} \\ f2_{2,4} \\ \vdots \\ f2_{2,n-3} \\ f2_{2,n-2} \\ f2_{2,n-1} \end{pmatrix}, \dots, F2,n-1 = \begin{pmatrix} f2_{n-1,1} \\ f2_{n-1,2} \\ f2_{n-1,3} \\ f2_{n-1,4} \\ \vdots \\ f2_{n-1,n-3} \\ f2_{n-1,n-2} \\ f2_{n-1,n-1} \end{pmatrix},$$

Method B. Let's replace the first order differential equations (2.3), (2.6) by three-point template to change the error $O(h^2)$:

$$\frac{\partial w_1(x,y)}{\partial x}\Big|_{x=a} = \frac{-1.5W1_{0,j} + 2W1_{1,j} - 0.5W1_{2,j}}{h} + O(h^2),$$
$$\frac{\partial w_2(x,y)}{\partial x}\Big|_{x=-a} = \frac{+1.5W2_{n,j} - 2W2_{n-1,j} + 0.5W2_{n-2,j}}{h} + O(h^2),$$
$$j = 1, 2, \cdots, n-1.$$

In case of (2.1) - (2.3) problem matrix form of algebraic equation system will have such view

1	C	D	Θ	Θ	•	•	•	Θ	Θ	(W1,1)		(F1,1)
l	E	B	E	Θ	•	•	•	Θ	Θ	W1,2		F1,2
l	Θ	E	B	E	Θ	•		Θ	Θ	W1,3		F1,3
I	Θ	Θ	E	B	E	Θ	•	Θ	Θ	W1,4		F1, 4
l	•	•	•	•	•	•	•	•			=	
I	•		•	•	•	•	•	•				
	Θ	Θ	•	•	Θ	E	B	E	Θ	W1, n - 3		F1, n-3
	Θ	Θ	•	•	•	Θ	E	B	E	W1, n-2		F1, n-2
	Θ	Θ	Θ	•	•	•	Θ	E	$_B$ /	$V_{1,n-1}$		$\left\langle F1, n-1 \right\rangle$

and in case of (2.4)-(2.6) problem we will have follow task

(B)	E	Θ	Θ	•	•	•	Θ	Θ	(W2,1)		(F2,1)	١
E	B	E	Θ	•	•	•	Θ	Θ	W2,2		F2,2	
Θ	E	B	E	Θ	•	•	Θ	Θ	W2,3		F2, 3	
Θ	Θ	E	B	E	Θ	•	Θ	Θ	W2, 4		F2,4	
•	•	•	•	•	•	•	•	•		=		,
•	•	•	•	•	•	•	•	•	•			
Θ	Θ	•	•	Θ	E	B	E	Θ	W2, n - 3		F2, n-3	
Θ	Θ	•	•	•	Θ	E	B	E	W2, n - 2		F2, n-2	
Θ	Θ	Θ	•	•	•	Θ	E	C /	$V_{2,n-1}$		$\setminus F2, n-1$,	/

where

	/ -8	3/3	1		0	0		•	•		0	0	
		1	-8/	3	1	0	•	•	•		0	0	
	(0	1	_	-8/3	1	0	•	•		0	0	
	(0	0		1	-8/3	1	0	•		0	0	
C =		•	•		•		•	•	•		•	•	
		•	•		•	•	•	•	•		•	•	
	(0	0		•	•	0	1	-8/3	3	1	0	
		0	0		•	•	•	0	1	_	8/3	1	
		0	0		0	•	•	•	0		1	-8/3	3/
		1	2/3	0	0	0				0	0)	
			0	2/3	0	0	•		•	0	0		
			0	0	2/3	0	0		•	0	0		
			0	0	0	2/3	0	0	•	0	0		
	D =	:	•	•	•	•	•	•	•	•	•		
			•	•	•	•	•	•	•	•	•		
			0	0	•	•	0	0	2/3	0	0		
			0	0	•	•	•	0	0	2/3	0		
			0	0	0		•		0	0	2/3	/	

In order to solve of the (2.7)-(2.8) nonlinear system of equations let's use the iterative method combined with factorization methods:

$$w3_{i+1}^{(k+1)} - 2w3_i^{(k+1)} + w3_{i-1}^{(k+1)} = h_3^2 f3_i / \left(m_0 + m_1 t k f(w3^{(k)})\right) \equiv F3_i^{(k)},$$

$$i = 1, 2, \cdots, 2n - 1; \quad k = 0, 1, 2, \cdots;$$

$$tkf(w3^{(k)}) = 0.5\left(\frac{w3_1^{(k)} - w3_0^{(k)}}{h}\right)^2 + \left(\frac{w3_2^{(k)} - w3_0^{(k)}}{2h}\right)^2 + \dots + \left(\frac{w3_{2n}^{(k)} - w3_{2n-2}^{(k)}}{2h}\right)^2 + 0.5\left(\frac{w3_{2n}^{(k)} - w3_{2n-1}^{(k)}}{h}\right)^2;$$

 $w3_i^{(0)}, i = 0, 1, 2, \cdots, 2n$ is the initial approach. Remark: we can take as initial approach

$$w3_0^{(0)} = a_2, \ w3_1^{(0)} = 0, \ w3_2^{(0)} = 0, \ \cdots, \ w3_{2n-1}^{(0)} = 0, \ w3_{2n}^{(0)} = a_1;$$

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For a finding in central points of required functions of a deflection it is received the following tree - diagonal system of the algebraic equations:

 $k=0,1,2,\cdots.$

The method of factorization is stabile, as $W3_1$ coefficients through $W3_2$ (in first equation), and $W3_{2n-1}$ through $W3_{2n-2}$ (in last equation) are equal 0.5.

It is created system of programs in MATLAB on the basis of the abovestated algorithm which is intended for a wide range of consumers.

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