

# AN ERROR OF THE ITERATION METHOD FOR A TIMOSHENKO NONHOMOGENEOUS EQUATION

J. Peradze<sup>\*,\*\*</sup>, Z. Tsiklauri<sup>\*\*</sup>

Ivane Javakhishvili Tbilisi State University\*  
0186 University Street 2, Tbilisi, Georgia  
Georgian Technical University\*\*  
77 Kostava Str., Tbilisi 0175, Tbilisi, Georgia

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*Abstract*

We consider the initial boundary value problem for an integro-differential equation describing the vibration of a beam. Using the Galerkin method and a symmetric difference scheme, the solution is approximates with respect to a spatial and a time variable. Thus the problem is reduced to a system of nonlinear discrete equations which is solved by the iteration method. The convergence of the method is proved.

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## 1 Statement of Problem

Let us consider the following initial boundary value problem

$$\frac{\partial^2 u}{\partial t^2} + \frac{\partial^4 u}{\partial x^4} - h \frac{\partial^4 u}{\partial x^2 \partial t^2} - \left( \lambda + \frac{1}{2L} \int_0^L \left( \frac{\partial u}{\partial x} \right)^2 dx \right) \frac{\partial^2 u}{\partial x^2} = f(x, t), \quad (1.1)$$

$$0 < x < L, \quad 0 < t \leq T,$$

$$u(x, 0) = u^0(x), \quad \frac{\partial u}{\partial t}(x, 0) = u^1(x), \quad (1.2)$$

$$u(0, t) = u(L, t) = 0, \quad \frac{\partial^2 u}{\partial x^2}(0, t) = \frac{\partial^2 u}{\partial x^2}(L, t) = 0,$$

$$0 \leq x \leq L, \quad 0 \leq t \leq T,$$

where  $h$  and  $\lambda$  are some non-negative constants,  $f(x, t)$ ,  $u^0(x)$  and  $u^1(x)$  are the given functions, and  $u(x, t)$  is the function to be defined. In the homogeneous case the equation (1.1) describing a dynamic beam was obtained by Henriques de Brito [1] and is a Timoshenko type equation [8].

Menzala and Zuazua [3], [4] arrived at the corresponding equation by making an additional assumption  $\lambda = 0$  and passing to the limit in the system of von Karman equations [2]

$$\begin{aligned} v_{tt} - \left( v_x + \frac{1}{2} w_x^2 \right)_x &= 0, \\ w_{tt} + w_{xxxx} - h w_{xxtt} - \left[ w_x \left( v_x + \frac{1}{2} w_x^2 \right) \right]_x &= 0 \end{aligned}$$

for a prismatic beam. In [5], the same authors write a generalized variant of the equation under discussion.

Note that the solvability of an operator equation, the particular case of which is the equation (1.1), is proved in [1].

In the present paper, we consider one numerical method of solution of the problem (1.1), (1.2). In [6], one can partly get acquainted with the bibliography on approximate algorithms for equations having nonlinearity analogous to that of (1.1).

## 2 The Algorithm

a. Galerkin method. A solution of the problem (1.1), (1.2) will be sought for as a finite sum

$$u_n(x, t) = \sum_{i=1}^n \frac{L}{i\pi} u_{ni}(t) \sin \frac{i\pi x}{L}, \quad (2.3)$$

where the coefficients  $u_{ni}(t)$  are defined by the Galerkin method from the system of ordinary differential equations

$$\begin{aligned} \left( h + \left( \frac{L}{i\pi} \right)^2 \right) u_{ni}''(t) + \\ + \left( \lambda + \left( \frac{i\pi}{L} \right)^2 + \frac{1}{4} \sum_{j=1}^n u_{nj}^2(t) \right) u_{ni}(t) &= f_i(t), \\ i &= 1, 2, \dots, n, \end{aligned} \quad (2.4)$$

with the initial conditions

$$\begin{aligned} u_{ni}(0) = u_i^0, \quad u_{ni}'(0) = u_i^1, \\ i = 1, 2, \dots, n. \end{aligned} \quad (2.5)$$

We have used here the notation

$$f_i(t) = \frac{2}{i\pi} \int_0^L f(x, t) \sin \frac{i\pi x}{L} dx,$$

$$u_i^p = \frac{2i\pi}{L^2} \int_0^L u^p(x) \sin \frac{i\pi x}{L} dx, \quad p = 0, 1, \quad i = 1, 2, \dots, n.$$

The problem of accuracy of this part of the algorithm is studied in [7] for the case  $f(x, t) = 0$ .

b. Difference scheme. On the time interval  $[0, T]$  we introduce the net with constant step  $\tau = \frac{T}{M}$  and nodes  $t_m = m\tau$ ,  $m = 0, 1, \dots, M$ .

Denote by  $u_{ni}^m$ ,  $m = 0, 1, \dots, M$ , a difference analogue of the function  $u_{ni}(t)$  from the expansion (2.3). To the system (2.4) we put into correspondence the symmetric implicit scheme

$$\begin{aligned} & \left( h + \left( \frac{L}{i\pi} \right)^2 \right) \frac{u_{ni}^{m+1} - 2u_{ni}^m + u_{ni}^{m-1}}{\tau^2} + \frac{1}{4} \sum_{p=0}^1 \left[ \lambda + \left( \frac{i\pi}{L} \right)^2 + \right. \\ & \left. + \frac{1}{8} \sum_{j=1}^n \left( (u_{nj}^{m+p})^2 + (u_{nj}^{m+p-1})^2 \right) \right] \left( u_{ni}^{m+p} + u_{ni}^{m+p-1} \right) = \\ & = \frac{1}{4} \sum_{p=0}^1 \left( f_i^{m+p} + f_i^{m+p-1} \right), \end{aligned} \quad (2.6)$$

$$m = 1, 2, \dots, M-1, \quad i = 1, 2, \dots, n,$$

and, using (2.4), replace the relations (2.5) by

$$\begin{aligned} u_{ni}^0 &= u_i^0, \\ u_{ni}^1 &= u_i^0 + \tau u_i^1 + \frac{\tau^2}{2} \left( h + \left( \frac{L}{i\pi} \right)^2 \right)^{-1} \left[ - \left( \lambda + \left( \frac{i\pi}{L} \right)^2 + \right. \right. \\ & \left. \left. + \frac{1}{4} \sum_{j=1}^n \frac{(u_{nj}^1)^2 + (u_{nj}^0)^2}{2} \right) \frac{u_{ni}^1 + u_{ni}^0}{2} + \frac{f_i^1 + f_i^0}{2} \right], \\ & i = 0, 1, \dots, n. \end{aligned} \quad (2.7)$$

Here we have used the notation  $f_i^m = f_i(t_m)$ ,  $m = 0, 1, \dots, M$ ,  $i = 1, 2, \dots, n$ .

c. Iteration method. Let us rewrite the system (2.6), (2.7) in the form

$$\begin{aligned}
u_{ni}^0 &= u_i^0, \quad i = 1, 2, \dots, n, \\
\frac{4}{\tau^2} \left( h + \left( \frac{L}{i\pi} \right)^2 \right) u_{ni}^m &+ \left[ \lambda + \left( \frac{i\pi}{L} \right)^2 + \right. \\
&+ \left. \frac{1}{8} \sum_{j=1}^n \left( (u_{nj}^m)^2 + (u_{nj}^{m-1})^2 \right) \right] (u_{ni}^m + u_{ni}^{m-1}) = \\
&= \frac{4}{\tau^2} \left( h + \left( \frac{L}{i\pi} \right)^2 \right) \sum_{p=0}^2 \tau^p a_{ni,p}^m, \\
m &= 1, 2, \dots, M, \quad i = 1, 2, \dots, n,
\end{aligned} \tag{2.8}$$

where

$$\begin{aligned}
a_{ni,0}^1 &= u_i^0, \quad a_{ni,1}^1 = u_i^1, \quad a_{ni,2}^1 = \frac{1}{4} \left( h + \left( \frac{L}{i\pi} \right)^2 \right)^{-1} (f_i^1 + f_i^0), \\
a_{ni,0}^m &= 2u_{ni}^{m-1} - u_{ni}^{m-2}, \quad a_{ni,1}^m = 0, \\
a_{ni,2}^m &= -\frac{1}{4} \left( h + \left( \frac{L}{i\pi} \right)^2 \right)^{-1} \left[ \lambda + \left( \frac{i\pi}{L} \right)^2 + \right. \\
&+ \left. \frac{1}{8} \sum_{j=1}^n \left( (u_{nj}^{m-1})^2 + (u_{nj}^{m-2})^2 \right) (u_{ni}^{m-1} + u_{ni}^{m-2}) - (f_i^m + 2f_i^{m-1} + f_i^{m-2}) \right], \\
m &= 2, 3, \dots, M.
\end{aligned}$$

We split the system (2.8) into subsystems corresponding to each  $m = 1, 2, \dots, M$  and will solve them individually by iteration

$$\begin{aligned}
\frac{4}{\tau^2} \left( h + \left( \frac{L}{i\pi} \right)^2 \right) u_{ni,k+1}^m &+ \\
&+ \left[ \lambda + \left( \frac{i\pi}{L} \right)^2 + \frac{1}{8} \left( (u_{ni,k+1}^m)^2 + (u_{ni}^{m-1})^2 \right) + \right. \\
&+ \left. \frac{1}{8} \sum_{\substack{j=1 \\ j \neq i}}^n \left( (u_{nj,k}^m)^2 + (u_{nj}^{m-1})^2 \right) \right] (u_{ni,k+1}^m + u_{ni}^{m-1}) = \\
&= \frac{4}{\tau^2} \left( h + \left( \frac{L}{i\pi} \right)^2 \right) \sum_{p=0}^2 \tau^p a_{ni,p}^m, \\
k &= 0, 1, \dots, \quad i = 1, 2, \dots, n.
\end{aligned} \tag{2.9}$$

Here  $u_{ni,k+l}^m$  denotes the  $(k+l)$ -th approximation of  $u_{ni}^m$ ,  $l = 0, 1$ .

Assume that we have already found  $u_{ni}^o$  for  $m = 1$ , and  $u_{ni}^{m-2}$  and  $u_{ni}^{m-1}$  for  $m > 1$ . For the sake of simplicity, we neglect the error corresponding to the values of these functions.

Since (2.9) is a cubic equation with respect to  $u_{ni,k+1}^m$ , the latter can be written in the explicit form

$$u_{ni,k+1}^m = -\frac{1}{3}u_{ni}^{m-1} + \sum_{l=1}^2 (-1)^{l+1} \left[ (-1)^l s_i + (s_i^2 + r_i^3)^{1/2} \right]^{1/3}, \quad (2.10)$$

$$k = 0, 1, \dots, \quad i = 1, 2, \dots, n,$$

where

$$r_i = \frac{1}{3} \left[ 8 \left( \lambda + \left( \frac{i\pi}{L} \right)^2 \right) + \frac{2}{3} (u_{ni}^{m-1})^2 + \sum_{\substack{j=1 \\ j \neq i}}^n \left( (u_{nj,k}^m)^2 + (u_{nj}^{m-1})^2 \right) + \frac{32}{\tau^2} \left( h + \left( \frac{L}{i\pi} \right)^2 \right) \right],$$

$$s_i = \frac{1}{3} u_{ni}^{m-1} \left[ 8 \left( \lambda + \left( \frac{i\pi}{L} \right)^2 \right) + \frac{10}{9} (u_{ni}^{m-1})^2 + \sum_{\substack{j=1 \\ j \neq i}}^n \left( (u_{nj,k}^m)^2 + (u_{nj}^{m-1})^2 \right) \right] - \frac{16}{\tau^2} \left( h + \left( \frac{L}{i\pi} \right)^2 \right) \left( \frac{1}{3} u_{ni}^{m-1} + \sum_{p=0}^2 \tau^p a_{ni,p}^m \right). \quad (2.11)$$

Thus the iteration method used here should be understood as counting by (2.10).

### 3 Error of the iteration method

Let us rewrite the system (2.10) as

$$u_{ni,k+1}^m = \varphi_i(u_{n1,k}^m, u_{n2,k}^m, \dots, u_{nn,k}^m), \quad (3.12)$$

$$k = 0, 1, \dots, i = 1, 2, \dots, n.$$

To estimate the error of the method (3.12) we need to consider the matrix-jacobian

$$J = \left( \frac{\partial \varphi_i}{\partial u_{nj,k}^m} \right)_{i,j=1}^n.$$

Taking into account (2.10)–(3.12), we conclude that the principal diagonal of the matrix  $J$  consists of zeros

$$\frac{\partial \varphi_i}{\partial u_{ni,k}^m} = 0,$$

as to the nondiagonal elements, for them we have

$$\begin{aligned} \frac{\partial \varphi_i}{\partial u_{nj,k}^m} &= -\frac{1}{9} u_{nj,k}^m \sum_{l=1}^2 \left[ (-1)^l s_i + (s_i^2 + r_i^3)^{\frac{1}{2}} \right]^{-\frac{2}{3}} \times \\ &\times \left[ 2u_{ni}^{m-1} + (-1)^l (2s_i u_{ni}^{m-1} + 3r_i^2) (s_i^2 + r_i^3)^{-\frac{1}{2}} \right], \quad i \neq j. \end{aligned}$$

Performing some transformations and using (2.11), we obtain

$$\begin{aligned} \left| \frac{\partial \varphi_i}{\partial u_{nj,k}^m} \right| &= \frac{4}{9r_i} |u_{nj,k}^m| \left( |u_{ni}^{m-1}| + \frac{|s_i|}{r_i} \right) \leq \\ &\leq \frac{\tau^2}{24} |u_{nj,k}^m| \left( h + \left( \frac{L}{i\pi} \right)^2 \right)^{-1} \times \\ &\times \left\{ \frac{\tau^2}{32} \left( h + \left( \frac{L}{i\pi} \right)^2 \right)^{-1} |u_{ni}^{m-1}| \left[ 8 \left( \lambda + \left( \frac{i\pi}{L} \right)^2 \right) + \right. \right. \\ &+ \sum_{\substack{l=1 \\ l \neq i}}^n \left. \left( (u_{nl,k}^m)^2 + (u_{nl}^{m-1})^2 \right) + \frac{10}{9} (u_{ni}^{m-1})^2 \right] + \\ &\left. + \frac{7}{6} |u_{ni}^{m-1}| + \sum_{p=0}^2 \tau^p |a_{ni,p}^m| \right\}. \end{aligned} \tag{3.13}$$

Let us apply the principle of compressed mappings. We define the vector and matrix norms by the expressions  $\sum_{i=1}^n |v_i|$  and  $\max_{1 \leq j \leq n} \sum_{i=1}^n |m_{ij}|$ , respectively, for  $v = (v_i)_{i=1}^n$ , and  $M = (m_{ij})_{i,j=1}^n$ .

Let in the vector domain

$$\left\{ (u_{ni})_{i=1}^n \in R^n \left| \sum_{i=1}^n |u_{ni} - u_{ni,0}^m| \leq \frac{1}{1-q} \sum_{i=1}^n |u_{ni,1}^m - u_{ni,0}^m| \right. \right\}, \tag{3.14}$$

the inequality

$$\max_{1 \leq j \leq n} \sum_{i=1}^n \left| \frac{\partial \varphi_i}{\partial u_{nj,k}^m} \right| < q$$

+

be fulfilled for  $q$ ,  $0 < q < 1$ . As follows from (3.13) and (3.14), for this it suffices that the relation

$$\alpha\tau^4 + \beta\tau^2 - \gamma \leq 0 \quad (3.15)$$

holds, where the following notation is used

$$\begin{aligned} \alpha &= \sum_{i=1}^n \left( h + \left( \frac{L}{i\pi} \right)^2 \right)^{-2} \left\{ \lambda + \left( \frac{i\pi}{L} \right)^2 + \frac{1}{8} \left[ \sum_{j=1}^n \left( |u_{ni,0}^m| + \right. \right. \right. \\ &\quad \left. \left. \left. + \frac{1}{1-q} |u_{ni,1}^m - u_{ni,0}^m| \right) \right]^2 + \frac{5}{36} \sum_{j=1}^n \left( u_{nj}^{m-1} \right)^2 \right\} |u_{ni}^{m-1}| + \\ &\quad + 4 \sum_{i=1}^n \left( h + \left( \frac{L}{i\pi} \right)^2 \right)^{-1} \left( \frac{\varepsilon}{4} |a_{ni,1}^m| + |a_{ni,2}^m| \right), \\ \beta &= \sum_{i=1}^n \left( h + \left( \frac{L}{i\pi} \right)^2 \right)^{-1} \left( \frac{14}{3} |u_{ni}^{m-1}| + |a_{ni,0}^m| + \frac{1}{\varepsilon} |a_{ni,1}^m| \right), \\ \gamma &= 96q \left[ \sum_{i=1}^n \left( |u_{ni,0}^m| + \frac{1}{1-q} |u_{ni,1}^m - u_{ni,0}^m| \right) \right]^{-1} \end{aligned}$$

and  $\varepsilon$  is an arbitrary positive number.

The relation (3.15) will be fulfilled if the set of the grid satisfies the inequality

$$\tau \leq \left[ \frac{1}{2\alpha} \left( -\beta + (\beta^2 + 4\alpha\gamma)^{\frac{1}{2}} \right) \right]^{\frac{1}{2}}.$$

In that case, in the domain (3.14) there exists a unique vector  $(u_{ni}^m)_{i=1}^n$  such that  $u_{ni}^m$ ,  $i = 1, 2, \dots, n$ , are a solution of the system (2.8), the sequence  $u_{ni,k}^m$  of the process (2.10) tends to  $u_{ni}^m$ ,  $i = 1, 2, \dots, n$ , as  $k \rightarrow \infty$ , whereas the method error decreases at a geometrical progression rate

$$\begin{aligned} \sum_{i=1}^n |u_{ni,k}^m - u_{ni}^m| &\leq \frac{q^k}{1-q} \sum_{i=1}^n |u_{ni,1}^m - u_{ni,0}^m|, \\ k &= 0, 1, \dots \end{aligned}$$

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