

THE MIXED PROBLEM OF THE THEORY OF ELASTICITY  
MIXTURE FOR A RECTANGLE WEAKENED BY UNKNOWN  
EQUALLY STRONG HOLES

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*Abstract*

In the present paper we investigate the mixed problem of statics in the linear theory of elasticity mixtures for a rectangle weakened by equally strong holes. Using the methods of the theory of elastic functions a stressed state of the plate, a form and mutual location of the hole contours are defined.

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1<sup>0</sup>. The homogeneous equation of statics of the theory of elastic mixture in the complex form is written as [3]

$$\frac{\partial^2 U}{\partial z \partial \bar{z}} + \mathcal{K} \frac{\partial^2 \bar{U}}{\partial \bar{z}^2} = 0, \quad (1)$$

where  $z = x_1 + ix_2$ ,  $\bar{z} = x_1 - ix_2$ ,  $\frac{\partial}{\partial z} = \frac{1}{2} \left( \frac{\partial}{\partial x_1} + i \frac{\partial}{\partial x_2} \right)$ ,  $\frac{\partial}{\partial \bar{z}} = \frac{1}{2} \left( \frac{\partial}{\partial x_1} - i \frac{\partial}{\partial x_2} \right)$ ,  $U = (u_1 + iu_2, u_3 + iu_4)^T$ ,  $u^1 = (u_1, u_2)^T$ ,  $u'' = (u_3, u_4)^T$  are particle displacements,

$$\begin{aligned} \mathcal{K} &= -\frac{1}{2}em^{-1}, \quad e = \begin{bmatrix} e_4 & e_5 \\ e_5 & e_6 \end{bmatrix}, \quad m^{-1} = \frac{1}{\Delta_0} \begin{bmatrix} m_3 & -m_2 \\ -m_2 & m_1 \end{bmatrix}; \\ \Delta_0 &= m_1 m_3 - m_2^2, \quad m_k = e_k + \frac{1}{2}e_{3+k}, \quad k = 1, 2, 3, \quad e_1 = a_2/d_2, \\ e_2 &= -c/d_2, \quad e_3 = a_1/d_2, \quad a_1 = \mu_1 - \lambda_5, \quad a_2 = \mu_2 - \lambda_5, \quad c = \mu_3 + \lambda_5, \\ d_2 &= a_1 a_2 - c^2, \quad e_1 + e_4 = b/d_1, \quad e_2 + e_5 = -C_0/d_1, \quad e_3 + e_4 = 1/d_1 \\ a &= a_1 + b_1, \quad b = a_2 + b_2, \quad c_0 = c + d, \quad b_1 = \mu_1 + \lambda_1 + \lambda_5 - \alpha_2 \rho_2 / \rho, \\ b_2 &= \mu_2 + \lambda_5 + \alpha_2 \rho_1 / \rho, \quad d = \mu_2 + \lambda_3 - \lambda_5 - \alpha_2 \rho_1 / \rho \equiv \mu_3 + \lambda_4 - \lambda_5 + \alpha_2 \rho_2 / \rho, \\ &\alpha_2 = \lambda_3 - \lambda_4, \quad \rho = \rho_1 + \rho_2, \quad d = ab - c_0^2. \end{aligned}$$

Here  $\rho_1$  and  $\rho_2$  partial densities, and  $\mu_1, \mu_2, \mu_3, \lambda_p, p = \overline{1, 5}$ , are constants characterizing physical properties [5].

In [2,3] M. Basheleishvili obtained the representations

$$U = (u_1 + iu_2, u_3 + iu_4)^T = m\varphi(z) + \frac{1}{2}ez\overline{\varphi'(z)} + \overline{\psi(z)}, \quad (2)$$

$$TU = \begin{pmatrix} (TU)_2 - i(TU)_1 \\ (TU)_4 - i(TU)_3 \end{pmatrix} = \frac{\partial}{\partial s(x)} \left[ (A - 2E)\varphi(z) + Bz\overline{\varphi'(z)} + 2\mu\overline{\psi(z)} \right], \quad (3)$$

where  $\varphi(z) = (\varphi_1, \varphi_2)^T$  and  $\psi(z) = (\psi_1, \psi_2)^T$  are arbitrary analytic vector-functions,

$$A = 2\mu m, \quad \mu = \begin{bmatrix} \mu_1 & \mu_3 \\ \mu_3 & \mu_2 \end{bmatrix}, \quad m = \begin{bmatrix} m_1 & m_2 \\ m_2 & m_3 \end{bmatrix}, \quad B = \mu e, \quad E = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix},$$

$\frac{\partial}{\partial s(x)} = -n_2 \frac{\partial}{\partial x_1} + n_1 \frac{\partial}{\partial x_2}$ ,  $n_1$  and  $n_2$  are the projections of the unit vector of the normal onto the axes  $ox_1$  and  $ox_2$ ;  $(Tu)_p$ ,  $p = \overline{1, 4}$ , are components of the stresses vector [2]

$$(TU)_1 = r'_{11}n_1 + r'_{21}n_2, \quad r'_{11} = a\theta' + c_0\theta'' - 2\frac{\partial}{\partial x_2}(\mu_1u_2 + \mu_3u_4),$$

$$r'_{21} = -a_1\omega' - c\omega' + 2\frac{\partial}{\partial x_1}(\mu_1u_2 + \mu_3u_4),$$

$$(TU)_2 = r'_{12}n_1 + r'_{22}n_2, \quad r'_{12} = a_1\omega' + c\omega'' + 2\frac{\partial}{\partial x_2}(\mu_1u_1 + \mu_3u_3),$$

$$r'_{22} = a\theta' + c_0\theta'' - 2\frac{\partial}{\partial x_1}(\mu_1u_1 + \mu_3u_3),$$

$$(TU)_3 = r''_{11}n_1 + r''_{21}n_2, \quad r''_{11} = c_0\theta' + b\theta'' - 2\frac{\partial}{\partial x_2}(\mu_3u_2 + \mu_2u_4),$$

$$r''_{21} = c\omega'a_2 - \omega'' + 2\frac{\partial}{\partial x_1}(\mu_3u_2 + \mu_2u_4),$$

$$(TU)_4 = r''_{12}n_1 + r''_{22}n_2, \quad r''_{12} = c\omega' + a_2\omega'' + 2\frac{\partial}{\partial x_2}(\mu_3u_1 + \mu_2u_3),$$

$$r''_{22} = c_0\theta' + b\theta'' - 2\frac{\partial}{\partial x_1}(\mu_3u_1 + \mu_2u_3);$$

$$\theta' = \operatorname{div} u' = \frac{\partial u_1}{\partial x_1} + \frac{\partial u_2}{\partial x_2}, \quad \theta'' = \operatorname{div} u'' = \frac{\partial u_3}{\partial x_1} + \frac{\partial u_4}{\partial x_2},$$

$$\omega' = \operatorname{rot} u' = \frac{\partial u_2}{\partial x_1} - \frac{\partial u_1}{\partial x_2}, \quad \omega'' = \operatorname{rot} u'' = \frac{\partial u_4}{\partial x_1} - \frac{\partial u_3}{\partial x_2}.$$

Let us now consider the vectors:

$$\stackrel{(1)}{\equiv} \tau(r'_{11}, r''_{11})^T, \quad \stackrel{(2)}{\equiv} \tau(r'_{22}, r''_{22})^T, \quad \tau = \stackrel{(1)}{\tau} + \stackrel{(2)}{\tau}, \quad (4)$$

$$\stackrel{(1)}{\eta} = (r'_{21}, r''_{21})^T, \quad \stackrel{(2)}{\eta} = (r'_{12}, r''_{12})^T, \quad \eta = \stackrel{(1)}{\eta} + \stackrel{(2)}{\eta}, \quad \varepsilon^* = \stackrel{(1)}{\eta} - \stackrel{(2)}{\eta}. \quad (5)$$

After lengthy but elementary calculations we obtain

$$\tau = \overset{(1)}{\tau} + \overset{(2)}{\tau} = 2(2E - A - B) \operatorname{Re} \Phi(z), \quad (6)$$

$$\varepsilon^* = \overset{(1)}{\eta} - \overset{(2)}{\eta} = 2(A - B - 2E) \operatorname{Im} \Phi(z), \quad (7)$$

$$\overset{(1)}{\tau} - \overset{(2)}{\tau} - i\eta = 2(B\bar{z}\phi'(z) + 2\mu\Psi(z)), \quad (8)$$

here  $\Phi(z) = \varphi'(z)$ ,  $\Psi(z) = \psi'(z)$ ;  $\det(2E - A - B) > 0$ , [4].

Now we consider the right orthogonal coordinate system  $(nS)$ . By  $n$  we denote the outer normal vector to  $L$  at point  $t = t_1 + it_2$ , and by  $S$  the tangent vector. Suppose that  $n = (n_1, n_2)^T = (\cos \alpha, \sin \alpha)^T$  and  $S = (-n_2, n_1)^T = (-\sin \alpha, \cos \alpha)^T$ , where  $\alpha = \alpha(t)$  is size of the angle made by the outer normal  $n$  and the  $ox_1$  axis.

Next we construct the vectors:

$$\sigma_n = \begin{pmatrix} (Tu)_1 n_1 + (Tu)_2 n_2 \\ (Tu)_3 n_1 + (Tu)_4 n_2 \end{pmatrix} = \overset{(1)}{\tau} \cos^2 \alpha + \overset{(2)}{\tau} \sin^2 \alpha + \eta \sin \alpha \cos \alpha, \quad (9)$$

$$\sigma_s = \begin{pmatrix} (Tu)_2 n_1 - (Tu)_1 n_2 \\ (Tu)_4 n_1 - (Tu)_3 n_2 \end{pmatrix} = \frac{1}{2}(\overset{(2)}{\tau} - \overset{(1)}{\tau}) \sin 2\alpha + \frac{1}{2}\eta \cos 2\alpha - \frac{1}{2}\varepsilon^*, \quad (10)$$

$$\sigma_s^* = \sigma_s + \frac{1}{2}\varepsilon^*, \quad (11)$$

$$\begin{aligned} \sigma_t &= \begin{pmatrix} [r'_{21} n_1 - r'_{11} n_2, & r'_{22} n_1 - r'_{12} n_2]^T S \\ [r''_{21} n_1 - r''_{11} n_2, & r''_{22} n_1 - r''_{12} n_2]^T S \end{pmatrix} = \\ &= \overset{(1)}{\tau} \sin^2 \alpha + \overset{(2)}{\tau} \cos^2 \alpha - \eta \sin \alpha \cos \alpha \end{aligned} \quad (12)$$

From (8)–(12) and (6)–(8) we obtain on  $L$

$$\sigma_n + \sigma_t = \overset{(1)}{\tau} + \overset{(2)}{\tau} = 2(2E - A - B) \operatorname{Re} \Phi(t), \quad (13)$$

$$\sigma_n - i\sigma_s = (2E - A)\overline{\Phi(t)} - B\Phi(t) + (B\bar{t}\Phi'(t) + 2\mu\Psi(t))e^{2i\alpha(t)}, \quad (14)$$

and with elementary calculation we get on  $L$

$$\sigma_n + 2\mu\left(\frac{\partial U_s}{\partial s} + \frac{U_n}{\rho_0}\right) + i\left[\sigma_s - 2\mu\left(\frac{\partial U_n}{\partial s} - \frac{U_s}{\rho_0}\right)\right] = 2\Phi(t), \quad (15)$$

where  $1/\rho_0$  is the curvature of the curve  $L$  at the point  $t = t_1 - it_2$ ,

$$U_n = \begin{pmatrix} u_1 n_1 + u_2 n_2 \\ u_3 n_1 + u_4 n_2 \end{pmatrix}, \quad U_s = \begin{pmatrix} u_2 n_1 - u_1 n_2 \\ u_4 n_1 - u_3 n_2 \end{pmatrix}. \quad (16)$$

(2), (3), (6), (8) and (13)–(15) represent analogues to Kolosov-Muskhelishvili formulas in the theory of elastic mixtures.

$2^0$ . In the present work we consider the similar problem which have been investigated in the plane theory of elasticity by R. Bantsuri and Sh. Mzhavanadze in [1].

Let a middle surface of an elastic isotropic of the mixture occupy on the plane  $z = x_1 + ix_2$  the  $(n + 1)$  connected domain whose outer boundary is formed by straight lines  $x_1 = \pm x_1^0$  and  $x_2 = \pm x_2^0$ , and inner boundary is a union of simple closed smooth contours (a rectangle with holes).

Suppose that on the outer boundary of the domain  $D$  the value of the vector (10) is equal to zero, i.e.  $\sigma_s = 0$ , the vector  $U_n$  (see (16<sub>1</sub>)) on the rectangle sides take constant values, and the inner boundary the value of the vector (9) i.e.  $\sigma_n = p = \text{const}$ .

Consider the problem: Find a stressed state of the plate, a form and mutual location of the hole contours so as the vector (12), i.e.  $\sigma_t$ , on them to take constant value.

For solving of the problem we use method given in [1].

In the case under consideration we assume that the domain  $D$  is symmetric with respect to the  $ox_1$ -axis. This allows us to consider a part of the domain  $D$  lying in the upper half-plane. We denote it by  $D_1$ .

Owing to the symmetry, for the domain  $D_1$  we have the same boundary conditions as for  $D$ . The mathematical ground of this fact can be found in [4] and [7].

Thus for the domain  $D_1$  we obtain the following boundary conditions:

$$\begin{aligned} \sigma_s = 0, ; U_n = U_0(t) \quad \text{on } L_1 + L_2, \\ \sigma_s = 0, \quad \sigma_n = P, \quad \sigma_t = K^0, \quad \text{on } L_0, \end{aligned} \quad (17)$$

where  $U_0(t)$  is the given piecewise constant vector-function, where  $P = (P_1, P_2)^T$  is the given and  $K^0 = (K_1^0, K_2^0)^T$  is an unknown constant. The value  $K^0$  will be defined later in solving the problem.  $L_0$  is a union of unknown arcs,  $L_1$  and  $L_2$  are the unions of segments which are parallel with respect to the  $ox_1$  and  $ox_2$ -axes.

$$\begin{aligned} L_1 = \bigcup_{k=0}^{n+2} A_{2k} A_{2k+1}, \quad L_2 = A_1 A_2 \cup A_{2n+3} A_{2n+4}, \\ L_0 = \bigcup_{k=1}^n A_{2k+1} A_{2k+2}, \quad A_0 = A_{2n+5} = ix_2^0, \quad A_1 = x_1^0 + ix_2^0, \\ A_2 = -x_1^0, \quad A_{2n+3} = x_1^0, \quad A_{2n+4} = x_1^0 + ix_2^0. \end{aligned}$$

The points and their affixes are denoted by one and the same symbols.

By virtue of (13)-(15) and the conditions (17) the stressed state of the body is described by two analytic vector-functions  $\phi(z) = (\phi_1, \phi_2)^T$  and  $\Psi(\zeta) = (\psi_1, \psi_2)^T$  which on the boundary of the domain satisfy the

conditions

$$\operatorname{Re} \Phi(t) = \frac{1}{2}(2E - A - B)^{-1}(K^0 + P), \quad t \in L_0, \quad (18)$$

$$\operatorname{Im} \Phi(t) = 0, \quad t \in L_1 + L_2, \quad (19)$$

$$(\overline{Bt\Phi'(t)} + 2\mu\Psi(t))e^{2i\alpha(t)} = P + B\Phi(t) + (A - 2E)\overline{\Phi}(t), \quad t \in L_0, \quad (20)$$

where  $\alpha(t)$  is the angle between the outer normal to the boundary of the domain  $D_1$  at the point  $t$  and the  $ox_1$ -axis. In our case  $\alpha(t) = 0$  or  $\alpha(t) = \pi$ , if  $t \in L_2$ ,  $\alpha(t) = \frac{\pi}{2}$  or  $\alpha(t) = -\frac{\pi}{2}$ , if  $t \in L_1$  and  $\alpha(t)$  is unknown if  $t \in L_0$ .

The functions  $\Phi_j(z)$  and  $\Psi_j(z)$ ,  $j = 1, 2$ , satisfy in neighborhoods of the points  $A_k$ ,  $k = \overline{1, 2n+4}$  the following conditions:

$$|\Phi_j(z)| < \operatorname{const} |z - c|^{-\delta}, \quad |\Psi_j(z)| < \operatorname{const} |z - c|^{-\delta}, \quad j = 1, 2, \quad 0 \leq \delta \leq 1. \quad (21)$$

Let the functions  $z = \omega(\zeta)$  map conformally the upper half-plane of the complex variable  $\zeta = \xi + i\xi_2$  onto the domain  $D_1$ . Here we use the following notation:  $\omega^{-1}(A_k) = a_k$ ,  $k = \overline{0, 2n+5}$ ,  $\omega^{-1}(L_k) = l_k$ ,  $k = \overline{0, 1, 2}$ . We may assume that  $a_0 = -\infty$ ,  $a_{2n+5} = +\infty$ ,  $a_2 = -1$  and  $a_{2n+3} = 1$ .

Since the contours of the hole are smooth, the function  $\omega(z)$  in the neighborhoods of the points ( $k = \overline{1, 2n+4}$ ) is representable in the form [1]

$$\omega(\zeta) = (\zeta - c)^{1/2}\omega_0(\zeta) + \omega(c), \quad (22)$$

where  $\omega_0(\zeta)$  is the function, holomorphic in the neighborhood of the point, and  $\omega(c) \neq 0$  ( $c$  denotes any of the points  $k = \overline{1, 2n+4}$ ). In the neighborhood of the point  $\zeta = \infty$  we have

$$\omega(\zeta) = c_0 + \frac{c_1}{\zeta} + \frac{c_2}{\zeta^2} + \dots, \quad (23)$$

where  $c_k$  ( $k = 0, 1, 2, \dots$ ) are the constants.

The change of the variable  $\zeta = \omega(\zeta)$  results in

$$e^{2i\alpha(t)} = -\omega'(\xi_1)/\overline{\omega'(\xi_1)}. \quad (24)$$

Taking into account the fact that  $z = \omega(\zeta)$  and also the condition (17), from (18) and (19) we easily obtain

$$\operatorname{Im} \Phi_0(\xi_1) = 0, \quad \text{on } l_1 + l_2; \quad \operatorname{Re} \Phi_0(\xi_1) = H, \quad \text{on } l_0; \quad (25)$$

where  $\Phi(z) = \Phi(\omega(z))$ ,  $H = \frac{1}{2}(2E - A - B)^{-1}(K^0 + p)$ ,  $\Phi_0 = (\Phi_{01}, \Phi_{02})$ .

Taking into consideration (21)-(23), we establish that  $\phi_0(\zeta)$  is bounded as  $\zeta \rightarrow \infty$  and in the neighborhood of the points  $a_k$ ,  $k = \overline{1, 2n+4}$ , satisfies the conditions

$$|\Phi_{oj}(\zeta)| < \operatorname{const} |\zeta - c|^{-\delta}, \quad 0 \leq \delta < \frac{1}{2}, \quad i = 1, 2.$$

Consider the vector-function  $F(\zeta) = \Phi_0(\zeta) - H$ . To define  $F(\zeta)$ , in view of (25), we get

$$\operatorname{Im} F(\xi_1) = 0 \quad \text{on } l_1 + l_2, \quad \operatorname{Re} F(\xi_1) = 0 \quad \text{on } l_0. \quad (26)$$

$F(\zeta)$  has the same estimates as  $\Phi_0(\zeta)$ .

(26) is, in fact, the homogeneous Keldysh-Sedov's problem for the half-plane and under the above conditions this problem has only a trivial solution  $F(z) = 0$ . Therefore

$$\Phi_0(\zeta) = H. \quad (27)$$

Tasking into account (27) and (24), the boundary condition (20) takes the form

$$h\omega'(\xi_1) + \overline{\omega'(\xi_1)\Psi_0(\xi_1)} = 0 \quad \text{on } l_0, \quad (28)$$

and by virtue of (17) we have (see (14))

$$\operatorname{Im} \Psi_0(\xi) = 0 \quad \text{on } l_1 + l_2; \quad (29)$$

where  $\Psi_0(\zeta) = \Psi(\omega(\zeta))$ ,  $h = \frac{\mu^{-1}}{4}(P - K^0)$ ,  $\Psi_0 = (\Psi_{01}, \Psi_{02})^T$ .

Obviously,

$$\operatorname{Re} \omega(\xi_1) = A(\xi_1) \quad \text{on } l_2; \quad \operatorname{Im} \omega(\xi_1) = B(\xi_1) \quad \text{on } l_1, \quad (30)$$

where  $A(\xi_1)$  and  $B(\xi_1)$  are the piecewise constant vector-functions, in particular,  $A(\xi_1) = x_1^0$ , for  $\xi_1 \in (a_{2n+3}, a_{2n+4})$ ,  $A(\xi_1) = -x_1^0$ , for  $\xi \in (a_1, a_2)$ ,  $B(\xi_1) = x_2^0$ , for,  $\xi_1 \in (-\infty, a_1) \cup (a_{2n+4}, \infty)$ ,  $B(\xi_1) = 0$ , for  $\xi_1 \in \bigcup_{k=1}^{n+1} (a_{2k}, a_{2k+1})$ .

Introduce the notation

$$W(\zeta) = \frac{1}{2} \omega'(\zeta)(\Psi_0(\zeta) + h), \quad \Omega(\zeta) = \frac{1}{2} \omega'(\zeta)(\Psi_0(\zeta) - h). \quad (31)$$

It is not difficult to state that  $|\zeta| \rightarrow \infty$ , as

$$W(\zeta) = O(\zeta^{-2}), \quad \Omega(\zeta) = O(\zeta^{-2}) \quad (32)$$

and in the neighborhood of the points  $a_k$ ,  $k = \overline{1, 2n+4}$ , satisfy the conditions

$$|W_j(\zeta)| < \text{const } |\zeta - c|^{-\delta}, \quad |\Omega_j(\zeta)| \leq \text{const } |\zeta - c|^{-\delta}, \quad 0 \leq \delta \leq \frac{1}{2}, \quad j = 1, 2. \quad (33)$$

Taking into account (28)-(33), to find  $W(\zeta)$  and  $\Omega(\zeta)$ , we obtain the boundary problem: Find the  $W(\zeta)$  and  $\Omega(\zeta)$ , analytic in the upper half-plane ( $\operatorname{Im} \zeta > 0$ ), which on the axis  $\xi_2 = 0$  satisfy the boundary conditions

$$\operatorname{Re} W(\xi_1) = 0 \quad \text{on } l_0 + l_2, \quad \operatorname{Im} W(\xi_1) = 0 \quad \text{on } l_1, \quad (34)$$

$$\operatorname{Im} \Omega(\xi_1) = 0 \quad \text{on } l_0 + l_1, \quad \operatorname{Re} \Omega(\xi_1) = 0 \quad \text{on } l_2, \quad (35)$$

and also the conditions (32) and (33) in the neighborhoods of the point  $\zeta = \infty$  and  $a_k$  ( $k = \overline{1, 2n+4}$ ).

The problems (32)-(35) are, in fact, the homogeneous Keldysh-Sedov's problem for a half-plane. The solution of the problems is given by the formulas ([5])

$$W(\zeta) = h\chi_1(\zeta)P_n(z), \quad \Omega(\zeta) = h\chi_2(\zeta)D_0, \quad (36)$$

where

$$\chi_1(\zeta) = \left[ \prod_{k=1}^{2n+4} (\zeta - a_k) \right]^{-\frac{1}{2}}, \quad (37)$$

$$\chi_2(\zeta) = \left[ (\zeta - a_1)(\zeta - a_2)(\zeta - a_{2n+3})(\zeta - a_{2n+4}) \right]^{-\frac{1}{2}};$$

$P_n(\zeta) = \sum_{k=0}^n C_k \zeta^k$ ,  $h = \frac{1}{4} \mu^{-1}(P - K^0)$ ;  $D_0, C_0, C_1, \dots, C_n$  are the real constants, under  $\chi_1(\zeta)$  and  $\chi_2(\zeta)$  are understood one-valued branches satisfying the conditions  $\chi_k(\zeta) < 0$ ,  $k = 1, 2$ , when  $\xi_2 = 0$  and  $\xi_1 > a_{2n+4}$ .

From (31) and (36) we find

$$\omega(z) = \int_{\zeta_0}^{\zeta} (\chi_1(\xi_1)P_n(\xi_1) - D_0\chi_2(\xi_1))d\xi_1 + \omega(z_0). \quad (38)$$

Taking into account the fact that  $\Psi_0(\zeta) = \Psi(\omega(\zeta)) = \Psi'(\omega(\zeta))$  and  $\Phi_0(\zeta) = \Phi(\omega(\zeta)) = \varphi'(\omega(\zeta))$  from (31), (36) and (27) we obtain

$$\psi(\omega(\zeta)) = h \int_{\zeta_0}^z (\chi_1(\xi_1)P_n(\xi_1) + D_0\chi_2(\xi_1))d\xi_1 + \psi(\zeta_0), \quad (39)$$

$$\varphi(\omega(\zeta)) = H\omega(\zeta) + C, \quad (40)$$

where  $\zeta_0$  is an arbitrary point of the domain  $\text{Im } z \geq 0$ ,  $C$  is a constant to be defined and  $H = \frac{1}{2}(2E - A - B)^{-1}(P + K^0)$ .

The above-formulated problem we can solve by the formulas (38)-(40).

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