

ON STABILITY AND CONVERGENCE OF SYMMETRIC
THREE-LAYER SEMIDISCRETE SCHEME FOR ABSTRACT
ANALOGUE OF NONLINEAR KIRCHHOFF WAVE EQUATION

J. Rogava, M. Tsiklauri

I. Vekua Institute of Applied Mathematics of
Iv. Javakhishvili Tbilisi State University
0143 University Street 2, Tbilisi, Georgia

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Abstract

In the present work Cauchy problem for abstract analogue of nonlinear Kirchhoff wave equation is considered. For approximate solution of this problem symmetric three-layer semi-discrete scheme is constructed. Stability and convergence for the offered scheme is shown.

Key words and phrases: nonlinear Kirchhoff wave equation, three-layer semidiscrete scheme.

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Let us consider the Cauchy problem for abstract hyperbolic equation in the Hilbert space H :

$$\frac{d^2u(t)}{dt^2} + A^2u(t) + a \left(\|A^{1/2}u\|^2 \right) Au(t) = 0, \quad t \in [0, T], \quad (1)$$

$$u(0) = \varphi_0, \quad \frac{du(0)}{dt} = \varphi_1. \quad (2)$$

where A is a self-adjoint (A does not depend on t), positively defined (generally unbounded) operator with the definition domain $D(A)$, which is everywhere dense in H , i.e. $\overline{D(A)} = H$, $A = A^*$ and

$$(Au, u) \geq \nu \|u\|^2, \quad \forall u \in D(A), \quad \nu = \text{const} > 0,$$

where by $\|\cdot\|$ and (\cdot, \cdot) are defined correspondingly the norm and scalar product in H ; $a \left(\|A^{1/2}u\|^2 \right) = \lambda + \|A^{1/2}u\|^2$, $\lambda > 0$; φ_0 and φ_1 are given vectors from H ; $u(t)$ is a continuous, twice continuously differentiable, searched function with values in H .

As in the linear case (see [1], T. 1.5 p. 301) $u(t)$ vector function with values in H , defined on the interval $[0, T]$ is called a solution of the problem

(1)-(2) if it satisfies the following conditions: (a) $u(t)$ is twice continuously differentiable in the interval $[0, T]$; (b) $u(t) \in D(A^2)$ for any t from $[0, T]$ and the function $A^2u(t)$ is continuous; (c) $u(t)$ satisfies equation (1) on the $[0, T]$ interval and the initial condition (2). Here continuity and differentiability is meant by metric H . Existence and uniqueness of the solution of the problem (1)-(2) is shown in [2].

Equation (1) is an abstract analogue of nonlinear Kirchhoff wave equation. Nonlinear Kirchhoff wave equation for stick has the following form:

$$\frac{\partial^2 u}{\partial t^2} + \frac{\partial^4 u}{\partial x^4} - \left(\lambda + \int_0^L u_\xi^2(\xi, t) d\xi \right) \frac{\partial^2 u}{\partial x^2} = 0.$$

We are searching solution of the problem (1)-(2) by the following semidiscrete scheme:

$$\begin{aligned} \frac{u_{k+1} - 2u_k + u_{k-1}}{\tau^2} + A^2 \frac{u_{k+1} + u_{k-1}}{2} \\ + a \left(\|A^{1/2}u_k\|^2 \right) \frac{Au_{k+1} + Au_{k-1}}{2} = 0, \end{aligned} \quad (3)$$

where $k = 1, \dots, n - 1$, $\tau = T/n$ ($n > 1$).

As an approximate solution $u(t)$ of problem (1)-(2) at point $t_k = k\tau$ we declare u_k -s, $u(t_k) \approx u_k$.

Theorem 1. *Vectors $(u_{k+1} - u_k)/\tau$, $A^{1/2}u_k$ and Au_k are equally bounded, i.e there exist constants M_1, M_2 and M_3 (independent of n) such that*

$$\begin{aligned} \left\| \frac{u_k - u_{k-1}}{\tau} \right\| &\leq M_1, \\ \|Au_k\| &\leq M_2, \quad \|A^{1/2}u_k\| \leq M_3, \quad k = 1, \dots, n. \end{aligned}$$

Proof. If we multiply scalarly both sides of equality (3) on vector $u_{k+1} - u_{k-1} = (u_{k+1} - u_k) + (u_k - u_{k-1})$, we obtain:

$$\begin{aligned} &\left\| \frac{u_{k+1} - u_k}{\tau} \right\|^2 + \frac{1}{2} \|Au_{k+1}\|^2 + \frac{1}{2} a \left(\|A^{1/2}u_k\|^2 \right) \|A^{1/2}u_{k+1}\|^2 \\ &= \left\| \frac{u_k - u_{k-1}}{\tau} \right\|^2 + \frac{1}{2} \|Au_{k-1}\|^2 + \frac{1}{2} a \left(\|A^{1/2}u_k\|^2 \right) \|A^{1/2}u_{k-1}\|^2. \end{aligned} \quad (4)$$

Let us introduce denotations:

$$\alpha_k = \left\| \frac{u_k - u_{k-1}}{\tau} \right\|^2, \quad \beta_k = \|Au_k\|^2, \quad \gamma_k = \|A^{1/2}u_k\|^2.$$

Then (4) will have the following form:

$$\begin{aligned} & \alpha_{k+1} + \frac{1}{2}(\beta_{k+1} + \beta_k) + \frac{1}{2}(\lambda + \gamma_k)\gamma_{k+1} \\ = & \alpha_k + \frac{1}{2}(\beta_k + \beta_{k-1}) + \frac{1}{2}(\lambda + \gamma_k)\gamma_{k-1}. \end{aligned}$$

Whence we have:

$$\lambda_{k+1} = \lambda_k + \varepsilon_k,$$

where

$$\begin{aligned} \lambda_k &= \alpha_k + \frac{1}{2}(\beta_k + \beta_{k-1}) + \frac{1}{2}(\lambda + \gamma_{k-1})\gamma_k, \\ \varepsilon_k &= \frac{1}{2}\lambda(\gamma_{k-1} - \gamma_k). \end{aligned}$$

Obviously from (4) we obtain:

$$\begin{aligned} \lambda_{k+1} &= \lambda_1 + (\varepsilon_1 + \varepsilon_2 + \dots + \varepsilon_k) \\ &= \lambda_1 + \frac{1}{2}\lambda((\gamma_0 - \gamma_1) + (\gamma_1 - \gamma_2) + \dots + (\gamma_{k-1} - \gamma_k)) \\ &= \lambda_1 + \frac{1}{2}\lambda(\gamma_0 - \gamma_k). \end{aligned}$$

Therefore we have:

$$\begin{aligned} & \alpha_{k+1} + \frac{1}{2}(\beta_{k+1} + \beta_k) + \frac{1}{2}(\lambda + \gamma_k)\gamma_{k+1} + \frac{1}{2}\lambda\gamma_k \\ = & \alpha_1 + \frac{1}{2}(\beta_1 + \beta_0) + \frac{1}{2}(\lambda + \gamma_1)\gamma_0 + \frac{1}{2}\lambda\gamma_0. \end{aligned}$$

From here it follow that α_k, β_k and γ_k are equally bounded. ■

The following theorem takes place (below everywhere c denotes positive constant):

Theorem 2. *Let u_k and \bar{u}_k be solutions of difference equation (3) corresponding to initial vectors (u_0, u_1) and (\bar{u}_0, \bar{u}_1) . Then for $z_k = u_k - \bar{u}_k$ the following estimates are true:*

$$\begin{aligned} \left\| A^{1/2} z_{k+1} \right\| &\leq e^{ct_k} \left(\sqrt{2} \left(\left\| A^{1/2} z_0 \right\| + \left\| A^{-1/2} \frac{\Delta z_0}{\tau} \right\| \right) \right. \\ &\quad \left. + \tau \left\| A^{1/2} \frac{\Delta z_0}{\tau} \right\| + c\tau \left\| A^{1/2} z_1 \right\| \right), \end{aligned} \quad (5)$$

$$\begin{aligned} \|Az_{k+1}\| &\leq e^{ct_k} \left(\sqrt{2} \left(\|Az_0\| + \left\| \frac{\Delta z_0}{\tau} \right\| \right) \right. \\ &\quad \left. + \tau \left\| A \frac{\Delta z_0}{\tau} \right\| + c\tau \|Az_1\| \right), \end{aligned} \quad (6)$$

$$\begin{aligned} \left\| \frac{\Delta z_k}{\tau} \right\| &\leq \|Az_0\| + \sqrt{2} \left\| \frac{\Delta z_0}{\tau} \right\| \\ &\quad + ct_k e^{ct_k} \left(\sqrt{2} \left(\|Az_0\| + \left\| \frac{\Delta z_0}{\tau} \right\| \right) \right) \\ &\quad + \tau \left\| A \frac{\Delta z_0}{\tau} \right\| + c\tau \|Az_1\|, \end{aligned} \tag{7}$$

where $k = 1, \dots, n - 1$, $\Delta z_k = z_{k+1} - z_k$.

Proof of **Theorem 2** is based on lemma, which we state below.

Let us consider in Hilbert space H the following difference equation:

$$\frac{u_{k+1} - 2u_k + u_{k-1}}{\tau^2} + A^2 \frac{u_{k+1} + u_{k-1}}{2} = f_k, \tag{8}$$

where $k = 1, \dots, n - 1$, u_0, u_1 and f_k are the given vectors of H .

The following lemma takes place.

Lemma 3. (see [3]) *For difference problem (8) the following estimates are true:*

$$\begin{aligned} \|A^{2s}u_{k+1}\| &\leq \sqrt{2} \left(\|A^{2s}u_0\| + \left\| A^{2s-1} \frac{\Delta u_0}{\tau} \right\| \right) + \tau \left\| A^{2s} \frac{\Delta u_0}{\tau} \right\| \\ &\quad + \tau \sum_{i=1}^k \|A^{2s-1}f_i\|, \quad 0 \leq s \leq 1/2, \end{aligned} \tag{9}$$

$$\left\| \frac{\Delta u_k}{\tau} \right\| \leq \|Au_0\| + \sqrt{2} \left\| \frac{\Delta u_0}{\tau} \right\| + \tau \sum_{i=1}^k \|f_i\|, \tag{10}$$

where $k = 1, \dots, n - 1$, $\Delta u_k = u_{k+1} - u_k$.

Let us return to proof of Theorem 2.

Proof of Theorem 2. From (3) it follows:

$$u_{k+1} = \tilde{L}_k u_k - u_{k-1}, \quad k = 1, \dots, n - 1, \tag{11}$$

where

$$\tilde{L}_k = 2 \left(I + \frac{\tau^2}{2} A^2 + \frac{\tau^2}{2} a \left(\|A^{1/2}u_k\|^2 \right) A \right)^{-1}.$$

Let us rewrite (11) as follows:

$$u_{k+1} = Lu_k - u_{k-1} + \left(\tilde{L}_k - L \right) u_k, \quad k = 1, \dots, n - 1, \tag{12}$$

where

$$L = 2 \left(I + \frac{\tau^2}{2} A^2 \right)^{-1}.$$

Obviously we have

$$\tilde{L}_k - L = \left(L^{-1} - \tilde{L}_k^{-1} \right) L \tilde{L}_k = -\frac{\tau^2}{4} a \left(\left\| A^{1/2} u_k \right\|^2 \right) A \tilde{L}_k.$$

Taking into account this transformation, from (11) it follows:

$$\frac{u_{k+1} - 2u_k + u_{k-1}}{\tau^2} + A^2 \frac{u_{k+1} + u_{k-1}}{2} = -\frac{1}{2} a \left(\left\| A^{1/2} u_k \right\|^2 \right) A \tilde{L}_k u_k. \quad (13)$$

It is obvious that according to (13) $z_k = u_k - \bar{u}_k$ will satisfy the following equation:

$$\frac{z_{k+1} - 2z_k + z_{k-1}}{\tau^2} + A^2 \frac{z_{k+1} + z_{k-1}}{2} = -\frac{1}{2} g_k, \quad (14)$$

where

$$\begin{aligned} g_k &= a \left(\left\| A^{1/2} u_k \right\|^2 \right) A \tilde{L}_k u_k - a \left(\left\| A^{1/2} \bar{u}_k \right\|^2 \right) A \bar{L}_k \bar{u}_k, \\ \bar{L}_k &= 2 \left(I + \frac{\tau^2}{2} A^2 + \frac{\tau^2}{2} a \left(\left\| A^{1/2} \bar{u}_k \right\|^2 \right) A \right)^{-1}. \end{aligned}$$

From (14) according to (9) it follows (correspondingly to $s = 1/4$ and $s = 1/2$):

$$\begin{aligned} \left\| A^{1/2} z_{k+1} \right\| &\leq \sqrt{2} \left(\left\| A^{1/2} z_0 \right\| + \left\| A^{-1/2} \frac{\Delta z_0}{\tau} \right\| \right) + \tau \left\| A^{1/2} \frac{\Delta u_0}{\tau} \right\| \\ &\quad + \frac{\tau}{2} \sum_{i=1}^k \left\| A^{-1/2} g_i \right\|, \end{aligned} \quad (15)$$

$$\begin{aligned} \left\| A z_{k+1} \right\| &\leq \sqrt{2} \left(\left\| A z_0 \right\| + \left\| \frac{\Delta z_0}{\tau} \right\| \right) + \tau \left\| A \frac{\Delta u_0}{\tau} \right\| \\ &\quad + \frac{\tau}{2} \sum_{i=1}^k \left\| g_i \right\|. \end{aligned} \quad (16)$$

The following representation is obvious

$$\begin{aligned} g_k &= \left(\left\| A^{1/2} u_k \right\| - \left\| A^{1/2} \bar{u}_k \right\| \right) \left(\left\| A^{1/2} u_k \right\| + \left\| A^{1/2} \bar{u}_k \right\| \right) \tilde{L}_k A u_k \\ &\quad - \frac{1}{4} \tau^2 a \left(\left\| A^{1/2} \bar{u}_k \right\|^2 \right) \left(\left\| A^{1/2} u_k \right\| - \left\| A^{1/2} \bar{u}_k \right\| \right) \\ &\quad \times \left(\left\| A^{1/2} u_k \right\| + \left\| A^{1/2} \bar{u}_k \right\| \right) A \tilde{L}_k \bar{L}_k A u_k \\ &\quad + a \left(\left\| A^{1/2} \bar{u}_k \right\|^2 \right) \bar{L}_k (A u_k - A \bar{u}_k). \end{aligned} \quad (17)$$

From (15) taking into account (17) it follows:

$$\begin{aligned}
 \|A^{1/2}z_{k+1}\| &\leq \sqrt{2} \left(\|A^{1/2}z_0\| + \left\| A^{-1/2} \frac{\Delta z_0}{\tau} \right\| \right) + \tau \left\| A^{1/2} \frac{\Delta u_0}{\tau} \right\| \\
 &+ \frac{\tau}{2} \sum_{i=1}^k \left(\|A^{1/2}z_i\| \left(\|A^{1/2}u_i\| + \|A^{1/2}\bar{u}_i\| \right) \|\tilde{L}_i\| \|A^{1/2}u_i\| \right. \\
 &+ \frac{1}{4} \tau^2 a \left(\|A^{1/2}\bar{u}_i\|^2 \right) \|A^{1/2}z_i\| \\
 &\times \left(\|A^{1/2}u_i\| + \|A^{1/2}\bar{u}_i\| \right) \|\tilde{L}_i\| \|A\bar{L}_i\| \|A^{1/2}u_i\| \\
 &\left. + a \left(\|A^{1/2}\bar{u}_i\|^2 \right) \|\bar{L}_i\| \|A^{1/2}z_i\| \right). \tag{18}
 \end{aligned}$$

If we take into account that $\|A^{1/2}u_k\|$ and $\|A^{1/2}\bar{u}_k\|$ are equally bounded and, in addition, $\|\tilde{L}_k\| \leq 2$, $\|\bar{L}_k\| \leq 2$ and

$$\frac{1}{4} \tau^2 a \left(\|A^{1/2}\bar{u}_k\|^2 \right) \|A\bar{L}_k\| \leq 1,$$

then from (15) we obtain:

$$\begin{aligned}
 \|A^{1/2}z_{k+1}\| &\leq \sqrt{2} \left(\|A^{1/2}z_0\| + \left\| A^{-1/2} \frac{\Delta z_0}{\tau} \right\| \right) + \tau \left\| A^{1/2} \frac{\Delta u_0}{\tau} \right\| \\
 &+ c\tau \sum_{i=1}^k \|A^{1/2}z_i\|. \tag{19}
 \end{aligned}$$

Let us introduce the following denotations

$$\begin{aligned}
 \delta_0 &= \sqrt{2} \left(\|A^{1/2}z_0\| + \left\| A^{-1/2} \frac{\Delta z_0}{\tau} \right\| \right) + \tau \left\| A^{1/2} \frac{\Delta u_0}{\tau} \right\|, \\
 \varepsilon_k &= \|A^{1/2}z_k\|.
 \end{aligned}$$

then the inequality (19) can be rewritten as:

$$\varepsilon_{k+1} \leq \delta_0 + c\tau \sum_{i=1}^k \varepsilon_i.$$

From here by the induction can be obtained (discrete analog of Gronwell's lemma):

$$\begin{aligned}
 \varepsilon_{k+1} &\leq (1 + c\tau)^{k-1} \delta_0 + c\tau (1 + c\tau)^{k-1} \varepsilon_1 \\
 &= (1 + c\tau)^{k-1} (\delta_0 + c\tau\varepsilon_1). \tag{20}
 \end{aligned}$$

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If we take into consideration that

$$(1 + c\tau)^k \leq e^{c(k\tau)} = e^{ct_k},$$

then from (20) we obtain (5).

From (16) with account of (17) analogously to (19) we obtain

$$\begin{aligned} \|Az_{k+1}\| &\leq \sqrt{2} \left(\|Az_0\| + \left\| \frac{\Delta z_0}{\tau} \right\| \right) + \tau \left\| A \frac{\Delta z_0}{\tau} \right\| \\ &\quad + c\tau \sum_{i=1}^k \left(\|A^{1/2}z_i\| + \|Az_i\| \right). \end{aligned}$$

From here, if we take into account that

$$\left\| A^{1/2}z_k \right\| = \left\| A^{-1/2} (Az_k) \right\| \leq \frac{1}{\sqrt{\nu}} \|Az_k\|, \quad (21)$$

then analogously to (5) we obtain (6).

Let us show the estimate (7). From (14) according to (10) it follows:

$$\left\| \frac{\Delta z_k}{\tau} \right\| \leq \|Az_0\| + \sqrt{2} \left\| \frac{\Delta z_0}{\tau} \right\| + c\tau \sum_{i=1}^k \left(\|A^{1/2}z_i\| + \|Az_i\| \right).$$

Obviously from here with account of (21) we obtain:

$$\left\| \frac{\Delta z_k}{\tau} \right\| \leq \|Az_0\| + \sqrt{2} \left\| \frac{\Delta z_0}{\tau} \right\| + c\tau \sum_{i=1}^k \|Az_i\|.$$

From here with account of (6) follows (7). ■

The following theorem takes place.

Theorem 4. *Let the following conditions be fulfilled: (a) $u_0 = \varphi_0$ and $\varphi_0 \in D(A^2)$; (b) $u_1 = \varphi_0 + \tau\varphi_1 + \frac{\tau^2}{2}\varphi_2$, $\varphi_2 = -\left(A^2\varphi_0 + a\left(\|A^{1/2}\varphi_0\|^2\right)A\varphi_0\right)$ and $\varphi_2 \in D(A)$; (c) Solution $u(t)$ of problem (1)-(2) is continuously differentiable to third degree including and $u'''(t)$ satisfies Holder's inequality with index λ ($0 < \lambda \leq 1$); (d) $u'(t) \in D(A^2)$ for every t — from $[0, T]$ and function $A^2u'(t)$ satisfy Holder inequality with parameter λ ($0 < \lambda \leq 1$). Then for error $\tilde{z}_k = u(t_k) - u_k$ the following estimate is true:*

$$\max_{1 \geq k \leq n-1} \|A\tilde{z}_k\| \leq c\tau^{1+\lambda}, \quad (22)$$

$$\max_{1 \geq k \leq n-1} \left\| \frac{\Delta \tilde{z}_k}{\tau} \right\| \leq c\tau^{1+\lambda}. \quad (23)$$

Proof.

Let us write down the equation (1) at point $t = t_k$ in the following form:

$$\frac{\Delta^2 u(t_{k-1})}{\tau^2} + A^2 \frac{u(t_{k+1}) + u(t_{k-1})}{2} + a \left(\left\| A^{1/2} u(t_k) \right\|^2 \right) \frac{Au(t_{k+1}) + Au(t_{k-1})}{2} = r_\tau(t_k), \quad (24)$$

where

$$\begin{aligned} r_\tau(t_k) &= r_{0,\tau}(t_k) + r_{1,\tau}(t_k) + r_{2,\tau}(t_k), \\ r_{0,\tau}(t_k) &= \frac{\Delta^2 u(t_{k-1})}{\tau^2} - u''(t_k), \\ r_{1,\tau}(t_k) &= \frac{1}{2} A^2 (\Delta^2 u(t_{k-1})), \\ r_{2,\tau}(t_k) &= \frac{1}{2} a \left(\left\| A^{1/2} u(t_k) \right\|^2 \right) A (\Delta^2 u(t_{k-1})). \end{aligned}$$

From (24) we have

$$u(t_{k+1}) = L_k u(t_k) - u(t_{k-1}) + \frac{\tau^2}{2} L_k r_\tau(t_k), \quad k = 1, \dots, n-1, \quad (25)$$

where

$$L_k = 2 \left(I + \frac{\tau^2}{2} A^2 + \frac{\tau^2}{2} a \left(\left\| A^{1/2} u(t_k) \right\|^2 \right) A \right)^{-1}.$$

Let us rewrite (25) in the form:

$$\begin{aligned} u(t_{k+1}) &= Lu(t_k) - u(t_{k-1}) + \frac{\tau^2}{2} Lr_\tau(t_k) + (L_k - L)u(t_k) \\ &+ \frac{\tau^2}{2} (L_k - L)r_\tau(t_k), \quad k = 1, \dots, n-1. \end{aligned} \quad (26)$$

Obviously we have

$$L_k - L = (L^{-1} - L_k^{-1})LL_k = -\frac{\tau^2}{4} a \left(\left\| A^{1/2} u(t_k) \right\|^2 \right) ALL_k.$$

Taking into account this transformation, from (26) it follows:

$$\begin{aligned} &\frac{u(t_{k+1}) - 2u(t_k) + u(t_{k-1}))}{\tau^2} + A^2 \frac{u(t_{k+1}) + u(t_{k-1}))}{2} \\ &= -\frac{1}{2} a \left(\left\| A^{1/2} u(t_k) \right\|^2 \right) AL_k u(t_k) \\ &+ r_\tau(t_k) - \frac{\tau^2}{4} a \left(\left\| A^{1/2} u(t_k) \right\|^2 \right) AL_k r_\tau(t_k). \end{aligned} \quad (27)$$

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By taking (13) from (27) we obtain:

$$\frac{\tilde{z}_{k+1} - 2\tilde{z}_k + \tilde{z}_{k-1}}{\tau^2} + A^2 \frac{\tilde{z}_{k+1} + \tilde{z}_{k-1}}{2} = -\frac{1}{2}\tilde{g}_k + \tilde{r}_\tau(t_k), \quad (28)$$

where

$$\begin{aligned} \tilde{g}_k &= a \left(\|A^{1/2}u(t_k)\|^2 \right) AL_k u(t_k) - a \left(\|A^{1/2}u_k\|^2 \right) A\tilde{L}_k u_k \\ \tilde{r}_\tau(t_k) &= r_\tau(t_k) - \frac{\tau^2}{4} a \left(\|A^{1/2}u(t_k)\|^2 \right) AL_k r_\tau(t_k). \end{aligned}$$

Analogously to (17) we have:

$$\begin{aligned} \tilde{g}_k &= \left(\|A^{1/2}u(t_k)\| - \|A^{1/2}u_k\| \right) \\ &\times \left(\|A^{1/2}u(t_k)\| + \|A^{1/2}u_k\| \right) L_k Au(t_k) \\ &- \frac{1}{4}\tau^2 a \left(\|A^{1/2}u_k\|^2 \right) \left(\|A^{1/2}u(t_k)\| - \|A^{1/2}u_k\| \right) \\ &\times \left(\|A^{1/2}u(t_k)\| + \|A^{1/2}u_k\| \right) AL_k \tilde{L}_k Au(t_k) \\ &+ a \left(\|A^{1/2}u_k\|^2 \right) \tilde{L}_k (Au(t_k) - Au_k). \end{aligned} \quad (29)$$

From (28) according to (9) with account of (29) we obtain:

$$\begin{aligned} \|A\tilde{z}_{k+1}\| &\leq \sqrt{2} \left(\|A\tilde{z}_0\| + \left\| \frac{\Delta\tilde{z}_0}{\tau} \right\| \right) + \tau \left\| A \frac{\Delta\tilde{z}_0}{\tau} \right\| \\ &+ \frac{\tau}{2} \sum_{i=1}^k \left(\|A^{1/2}\tilde{z}_i\| \left(\|A^{1/2}u(t_i)\| + \|A^{1/2}u_i\| \right) \right. \\ &\times \|L_i\| \|Au(t_i)\| + \frac{1}{4}\tau^2 a \left(\|A^{1/2}u_i\|^2 \right) \|A^{1/2}\tilde{z}_i\| \\ &\times \left(\|A^{1/2}u(t_i)\| + \|A^{1/2}u_i\| \right) \|L_i\| \|A\tilde{L}_i\| \|Au(t_i)\| \\ &\left. + a \left(\|A^{1/2}u_i\|^2 \right) \|\tilde{L}_i\| \|A\tilde{z}_i\| \right) + \tau \sum_{i=1}^k \|\tilde{r}_\tau(t_i)\|. \end{aligned} \quad (30)$$

If we take into account that $\|A^{1/2}u(t_k)\|$, $\|Au(t_k)\|$ and $\|A^{1/2}u_k\|$ are equally bounded and, in addition, $\|\tilde{L}_k\| \leq 2$, $\|L_k\| \leq 2$, $\|A^{1/2}\tilde{z}_k\| \leq \frac{1}{\sqrt{\nu}} \|A\tilde{z}_k\|$ and

$$\frac{1}{4}\tau^2 a \left(\|A^{1/2}u_k\|^2 \right) \|A\tilde{L}_k\| \leq 1,$$

then from (30) we obtain:

$$\begin{aligned} \|A\tilde{z}_{k+1}\| &\leq \sqrt{2} \left(\|A\tilde{z}_0\| + \left\| \frac{\Delta\tilde{z}_0}{\tau} \right\| \right) + \tau \left\| A \frac{\Delta\tilde{z}_0}{\tau} \right\| \\ &\quad + c\tau \sum_{i=1}^k \|A\tilde{z}_i\| + \tau \sum_{i=1}^k \|\tilde{r}_\tau(t_i)\|. \end{aligned} \tag{31}$$

From here, according to discrete analog of Gronwell's lemma, we obtain:

$$\begin{aligned} \|A\tilde{z}_{k+1}\| &\leq e^{c_0 t_k} \left(\sqrt{2} \left(\|A\tilde{z}_0\| + \left\| \frac{\Delta\tilde{z}_0}{\tau} \right\| \right) + \tau \left\| A \frac{\Delta\tilde{z}_0}{\tau} \right\| \right. \\ &\quad \left. + c\tau \|A\tilde{z}_1\| + \tau \sum_{i=1}^k \|\tilde{r}_\tau(t_i)\| \right). \end{aligned} \tag{32}$$

It is obvious that the following inequality is true:

$$\begin{aligned} \|\tilde{r}_\tau(t_k)\| &= \left\| r_\tau(t_k) - \frac{\tau^2}{4} a \left(\left\| A^{1/2} u_n(t_k) \right\|^2 \right) AL_k r_\tau(t_k) \right\| \\ &\leq \|r_\tau(t_k)\| + \frac{\tau^2}{4} a \left(\left\| A^{1/2} u_n(t_k) \right\|^2 \right) \|AL_k\| \|r_\tau(t_k)\| \\ &\leq 2 \|r_\tau(t_k)\| \leq 2 (\|r_{0,\tau}(t_k)\| + \|r_{1,\tau}(t_k)\| + \|r_{2,\tau}(t_k)\|). \end{aligned} \tag{33}$$

According to how smooth is function $u(t)$, the following formulas are true:

$$\begin{aligned} \frac{\Delta^2 u(t_{k-1})}{\tau^2} - u''(t_k) &= \frac{1}{\tau^2} \int_{t_k}^{t_{k+1}} \int_{t_k}^t \int_{t_k}^s (u'''(\xi) - u'''(t_k)) d\xi ds dt + \\ &\quad \frac{1}{\tau^2} \int_{t_{k-1}}^{t_k} \int_{t_{k-2}}^t \int_{t_{k-1}}^s (u'''(t_k) - u'''(\xi)) d\xi ds dt, \end{aligned} \tag{34}$$

$$\begin{aligned} \Delta^2 u(t_{k-1}) &= \int_{t_k}^{t_{k+1}} (u'(t) - u'(t_k)) dt \\ &\quad + \int_{t_{k-1}}^{t_k} (u'(t_k) - u'(t)) dt, \end{aligned} \tag{35}$$

$$u(t_1) = u_0 + \tau u'(0) + \int_0^\tau (u'(t) - u'(0)) dt, \tag{36}$$

$$u(t_1) = u_0 + \tau u'(0) + \frac{\tau^2}{2} u''(0) \tag{37}$$

+

$$+ \int_0^\tau \int_0^t \int_0^s u'''(\xi) d\xi ds dt.$$

According to conditions (a), (b) and (d) of Theorem 4, from (36) it follows:

$$\begin{aligned} \|A(\Delta\tilde{z}_0)\| &= \|A(\tilde{z}_1 - \tilde{z}_0)\| = \|A\tilde{z}_1\| = \|A(u(t_1) - u_1)\| \\ &= \left\| -\frac{\tau^2}{2}A\varphi_2 + \int_0^\tau A(u'(t) - u'(0)) dt \right\| \leq c\tau^{1+\lambda}. \end{aligned} \quad (38)$$

According to conditions (a), (b) and (c) of Theorem 4, from (37) it follows:

$$\left\| \frac{\Delta\tilde{z}_0}{\tau} \right\| = \frac{1}{\tau} \|u(t_1) - u_1\| = \frac{1}{\tau} \int_0^\tau \int_0^t \int_0^s \|u'''(\xi)\| d\xi ds dt \leq c\tau^2. \quad (39)$$

According to condition (c) of Theorem 4, from (34) it follows:

$$\|r_{0,\tau}(t_k)\| = \left\| \frac{\Delta^2 u(t_{k-1})}{\tau^2} - u''(t_k) \right\| \leq c\tau^{1+\lambda}. \quad (40)$$

According to condition (c) of Theorem 4, from (35) it follows:

$$\|r_{j,\tau}(t_k)\| \leq c\tau^{1+\lambda}, \quad j = 1, 2. \quad (41)$$

From (33), with account of inequalities (40)-(41), it follows:

$$\|\tilde{r}_\tau(t_k)\| \leq c\tau^{1+\lambda}. \quad (42)$$

From (32), with account of inequalities (38),(39) and (42), follows (22).

Now let us show the estimate (23). From (28) according to (10), analogously to (31), it is obtained:

$$\left\| \frac{\Delta\tilde{z}_k}{\tau} \right\| \leq \|A\tilde{z}_0\| + \sqrt{2} \left\| \frac{\Delta\tilde{z}_0}{\tau} \right\| + c\tau \sum_{i=1}^k \|A\tilde{z}_i\| + \tau \sum_{i=1}^k \|\tilde{r}_\tau(t_i)\|.$$

From here with account of estimates (38),(39), (42) and (22), we obtain (23) ■

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